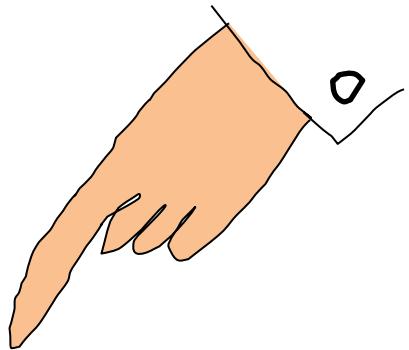
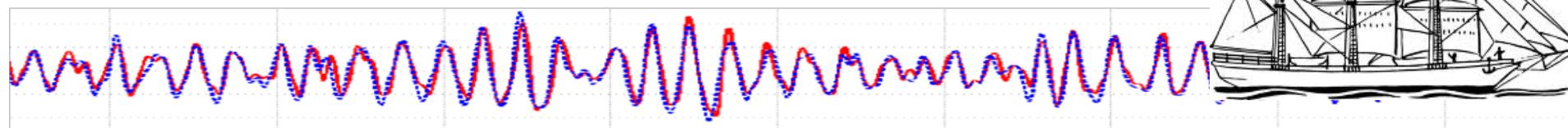


HaWaSSI

Hamiltonian Wave-Ship-Structure Interaction

Brenny van Groesen

University of Twente
&
LabMath-Indonesia



H aAB
WaSSI

Analytic Boussinesq

Andonowati
Lie She Liam
Andy Schauf
Nida Latifah
Ruddy Kurnia

Variational Boussinesq Model

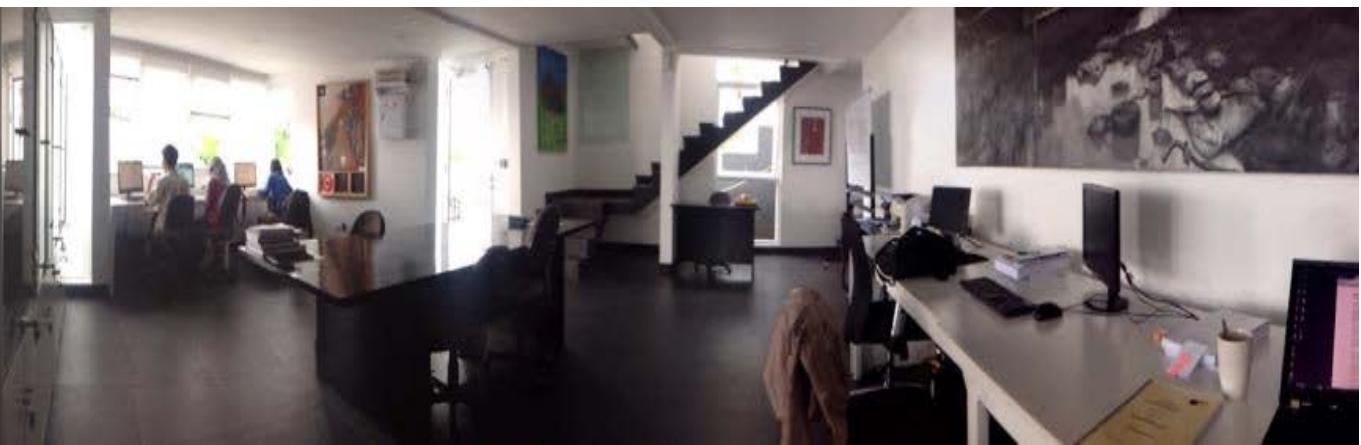
Gert Klopman
Ivan Lakhturov
Didit Adytia
Wenny Kristina
Mourice Woran

VBM
HaWaSI

Sea states from radar images
Andreas Wijaya



LabMath-Indonesia (Bandung)



Lawangwangi



Motivation

Modelling & simulation

- Many codes available for 'wave' simulations (irrotational flow)
 - Full Euler codes : CFD
 - Approximate models to avoid direct calculation of interior Laplace problem, e.g.
 - SWASH (vertical layers),
 - Boussinesq-type equations
(dispersion approx. with algebraic diff.operator)
- With **HaWaSSI** we aim to exploit some basic math structures:
 - Dynamics is Hamiltonian system in surface variables
(Boussinesq, exact energy conservation)
 - Laplace \leftrightarrow Dirichlet principle
 \rightarrow consistent approximation in functional, symmetry in eqn's
- Two versions:
 - **AB**: Fourier expansion (global \rightarrow local), exact dispersion
 - **VBM**: pcw-lin splines in FE, optimized dispersion

Contents

- Show performance
- Explain math background



Simulations for Coastal Engineering applications

Essential topics for simulation

WAVES

- DISPERSION (from deep sea to run-up at the coast)
- Nonlinearity, Breaking & set-up, freak waves
- Coastal run-up and harbour entrance
- Infragravity waves (for LNG in shallow water)

SHIP

- Motion (in waves), ship-interactions, near quay
- Mooring
- Ship waves (entering harbour, coast)

Comparison with experiments



Deltares
Enabling Delta Life



TU Delft



Test Cases & simulations

Validation wave tank (1HD)

- Irregular waves above Varying bottom
- Freak waves, Focussing waves
- Deep water breaking
- Bathymetry induced breaking

Validation wave basin (2HD)

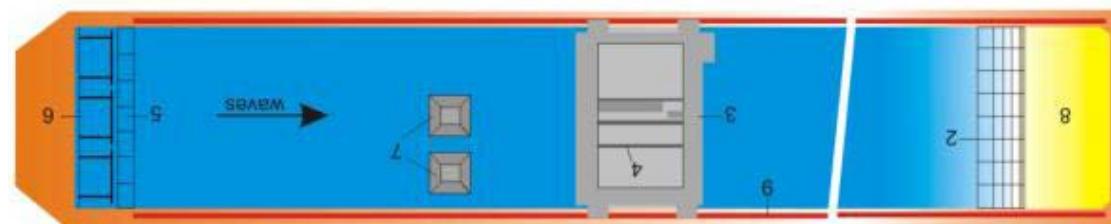
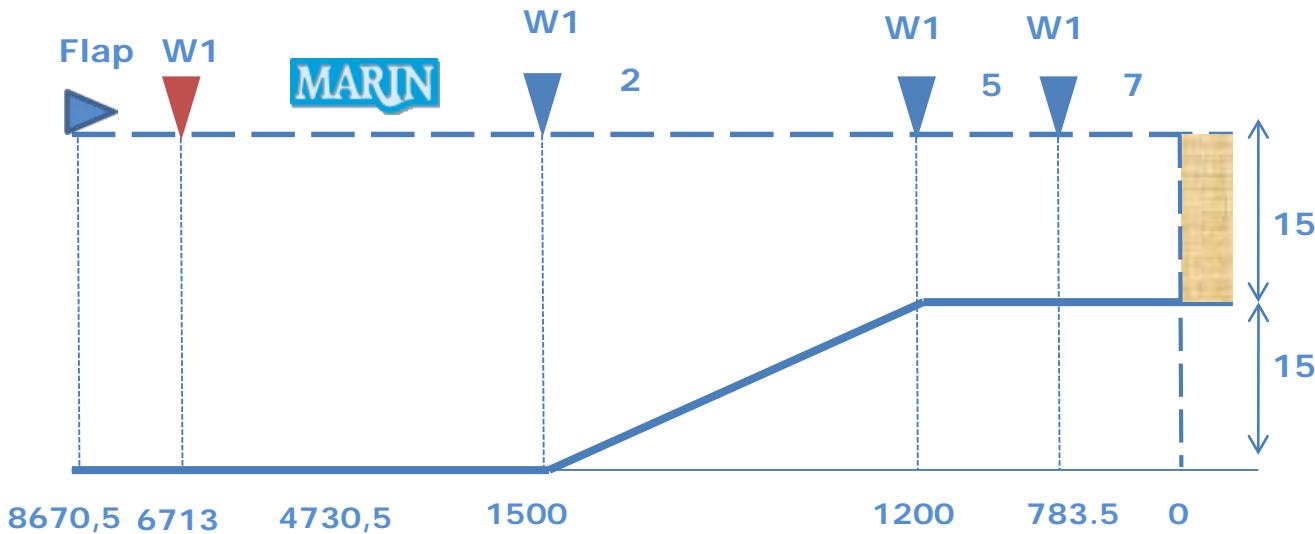
- Harbour: Limassol

Other simulations (2HD)

- Cilacap: infragravity waves
- Jakarta sea dike

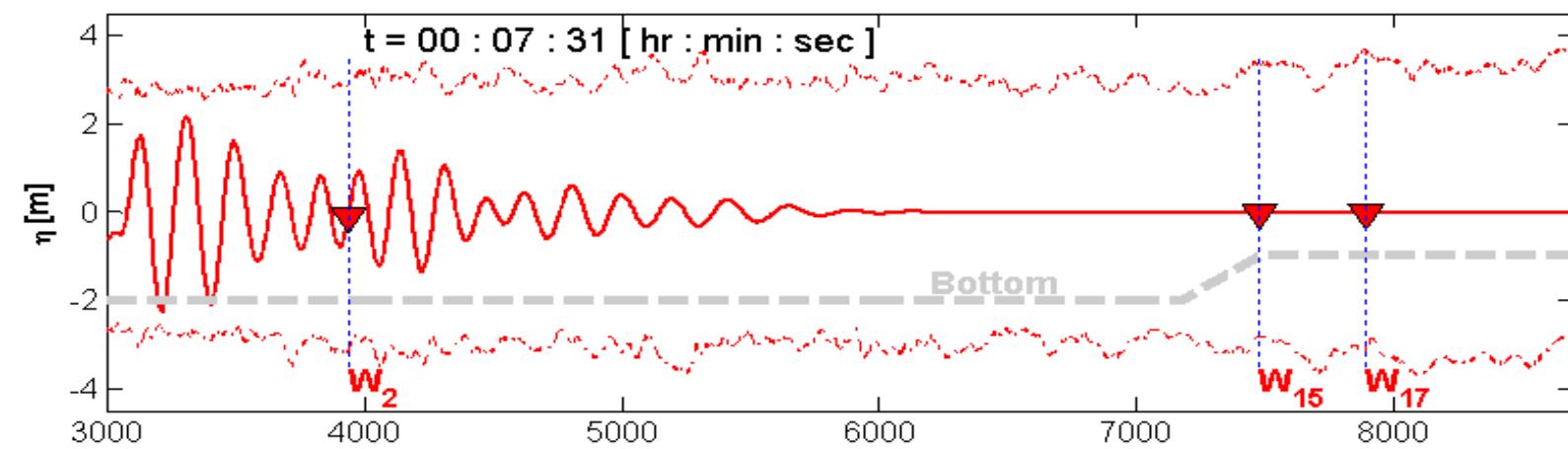
Experiment of irregular waves in
MARIN hydrodynamic lab
scale of 1:50

Period $\approx 12.2\text{s}$
 Wavelength $\approx 180\text{m}$ (at $h = 30\text{m}$)
 $\approx 130\text{m}$ (at $h = 15\text{m}$)

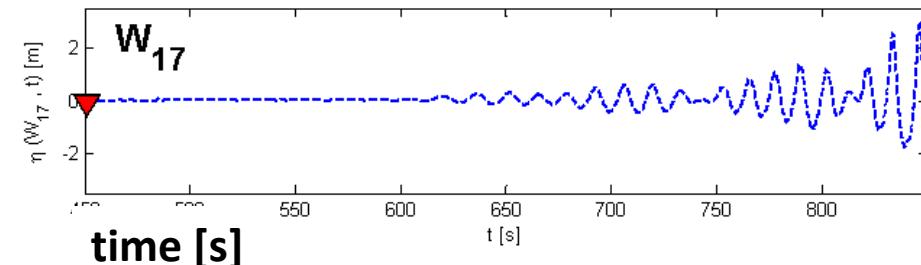
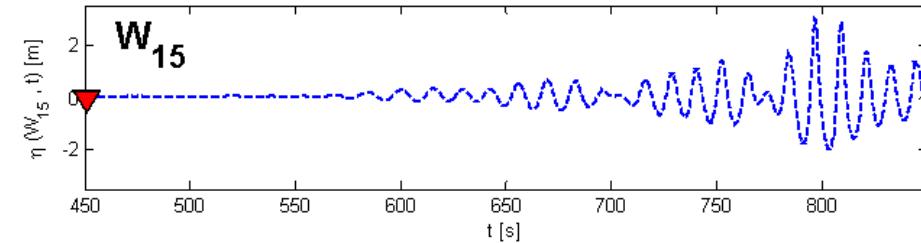
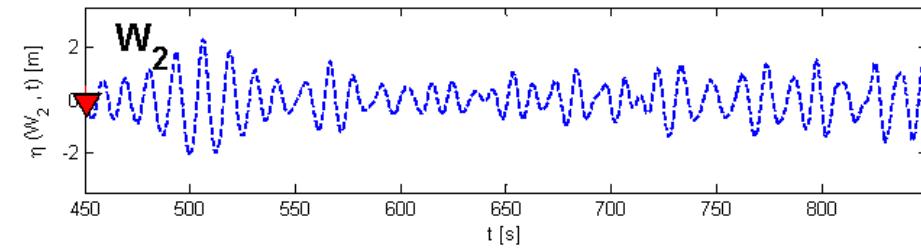


- ▼ : Buoy(s)
- - - : Experiment
- : Simulation

HAWAII Simulations vs Experiments



Signals

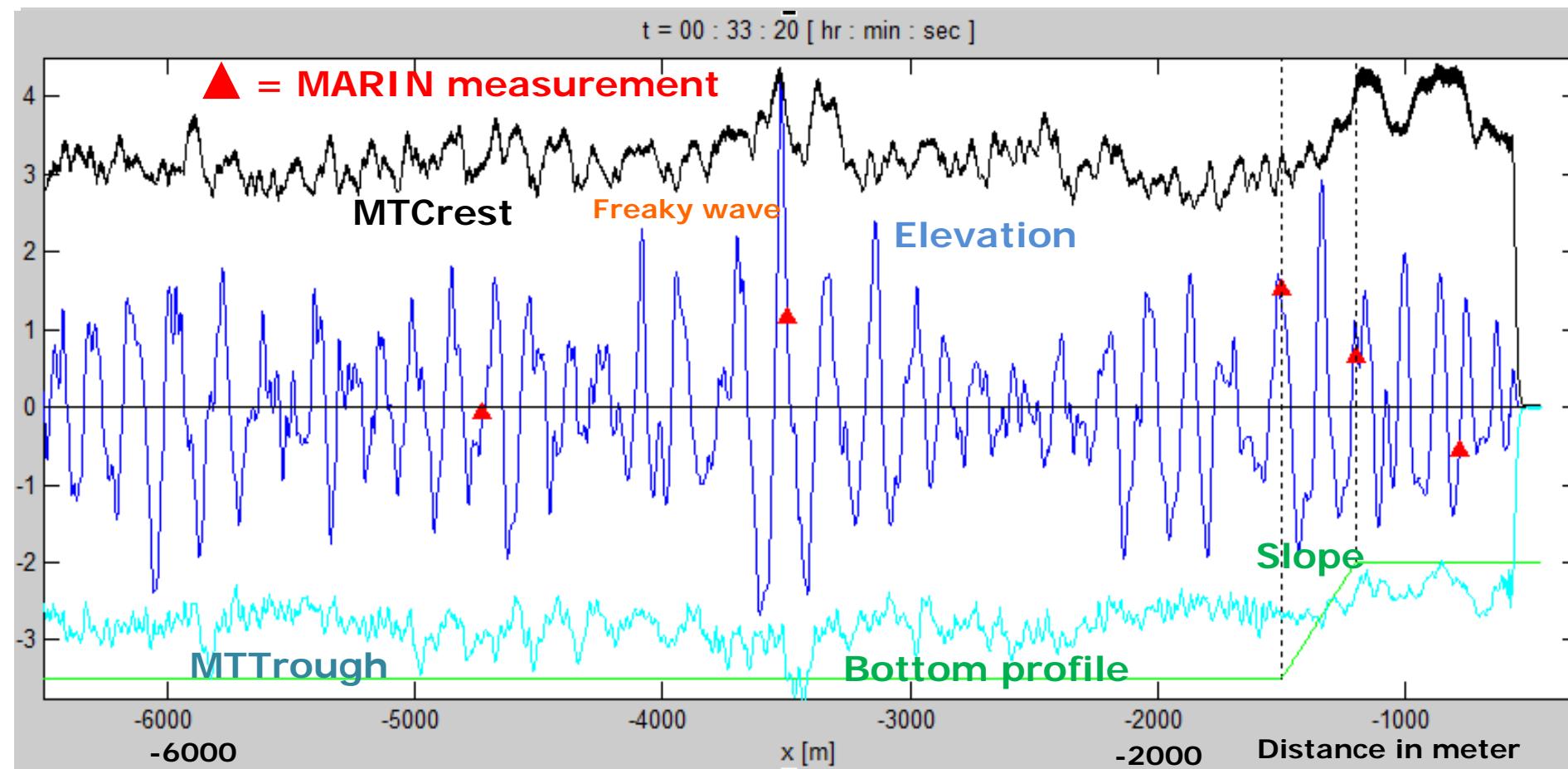


Irregular waves, MARIN Bench 103001

FREAK WAVES

- 3hrs time signal, approx. 1000 waves
- Period: 12s, Hs= 3m

Comparison Exp-Simul at W2, W9, W12, W15 and W17

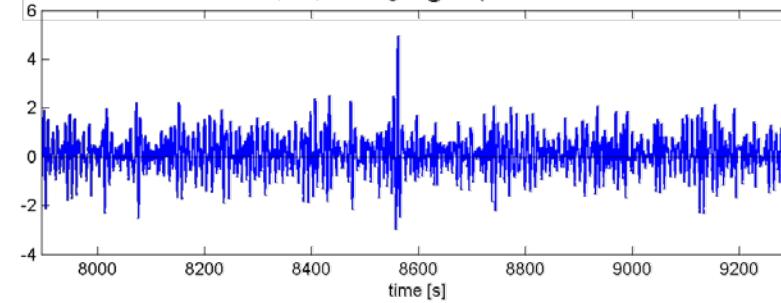
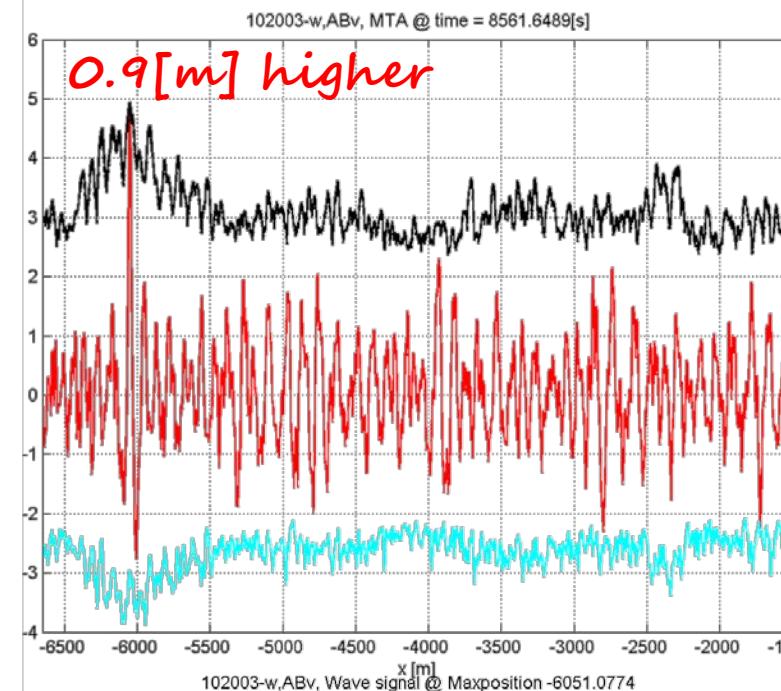


FW-analysis MARIN

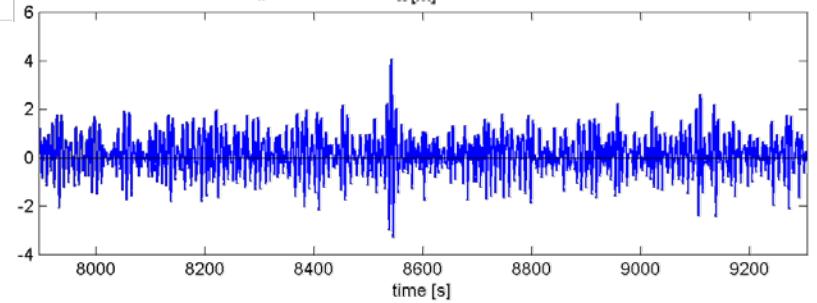
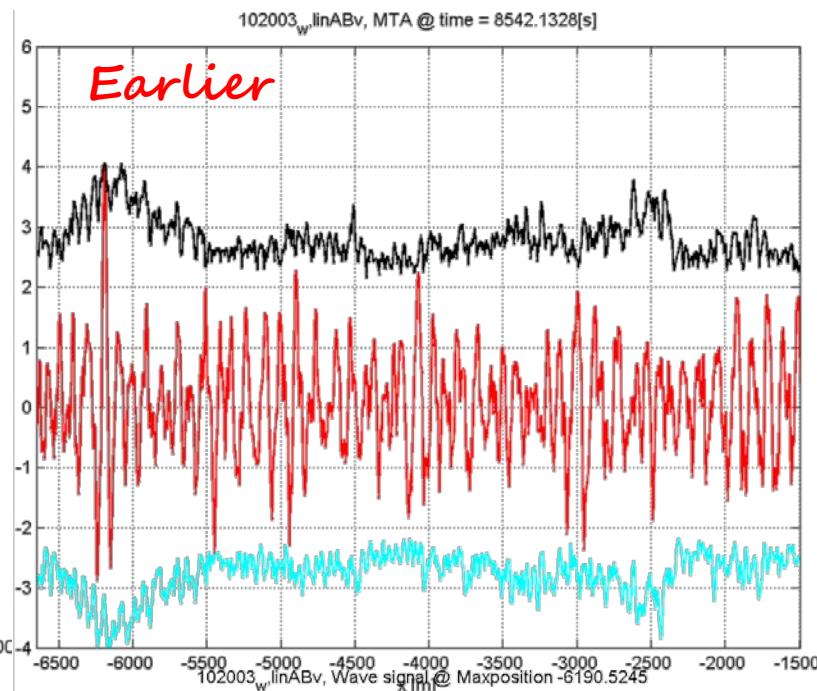
102003

date	18-Jun-11	02-Jul-11
wavename	102003_w	102003_w
Depth	30	
PeakPeriod	8.26	
Wavelength	101.55	
HsTot	3.07	
DynModel	NONlin	ABv LINEAR
Freak analysis	--	--
Xfr	-6051.08	-6190.52
Tfr	8561.65	8542.13
Crestheight	4.94	4.07
Troughdepth	-2.98	-2.90
Waveheight	7.92	6.97
WH/Hs	2.58	2.27

NONlin SIMULATIONS



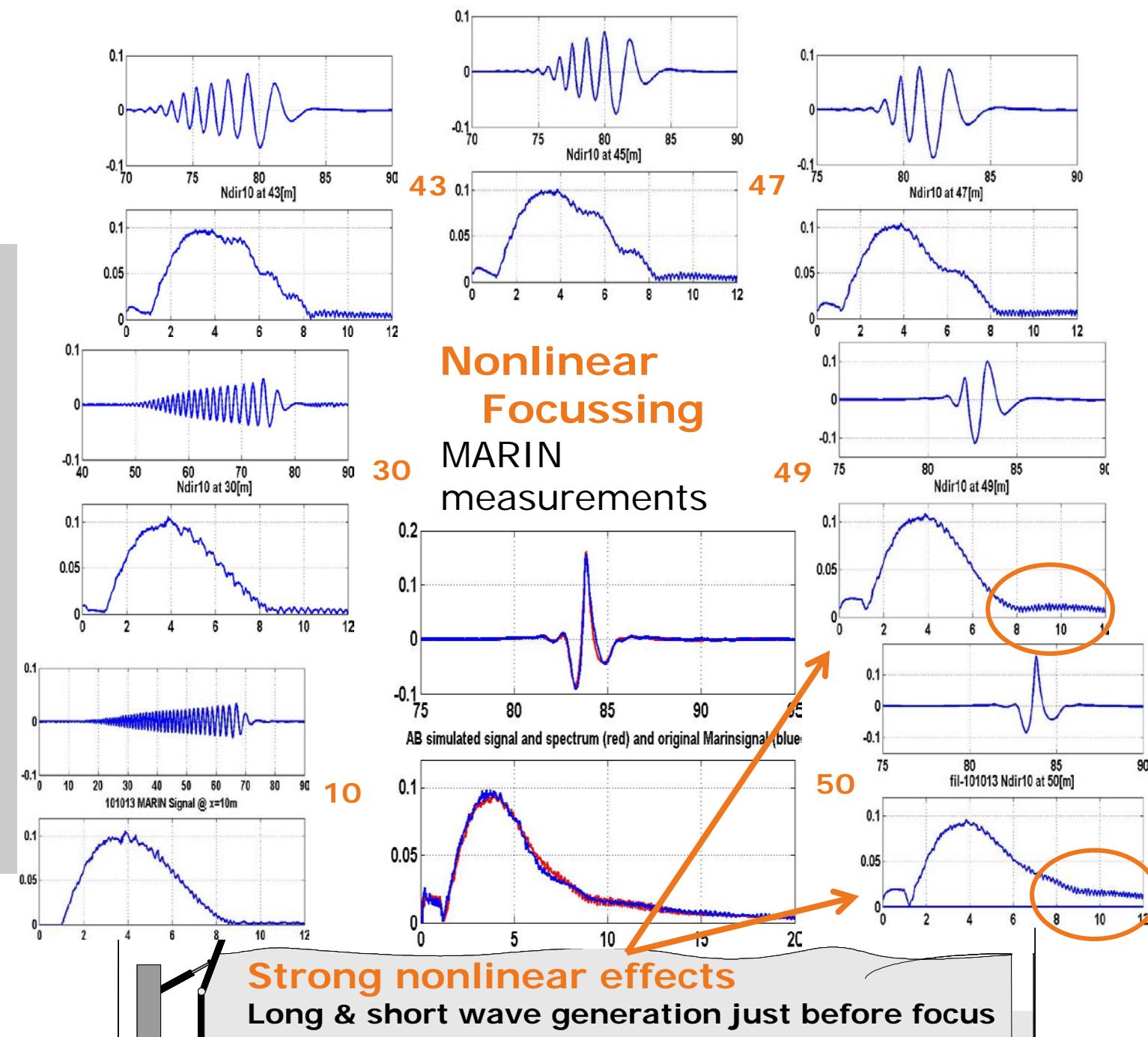
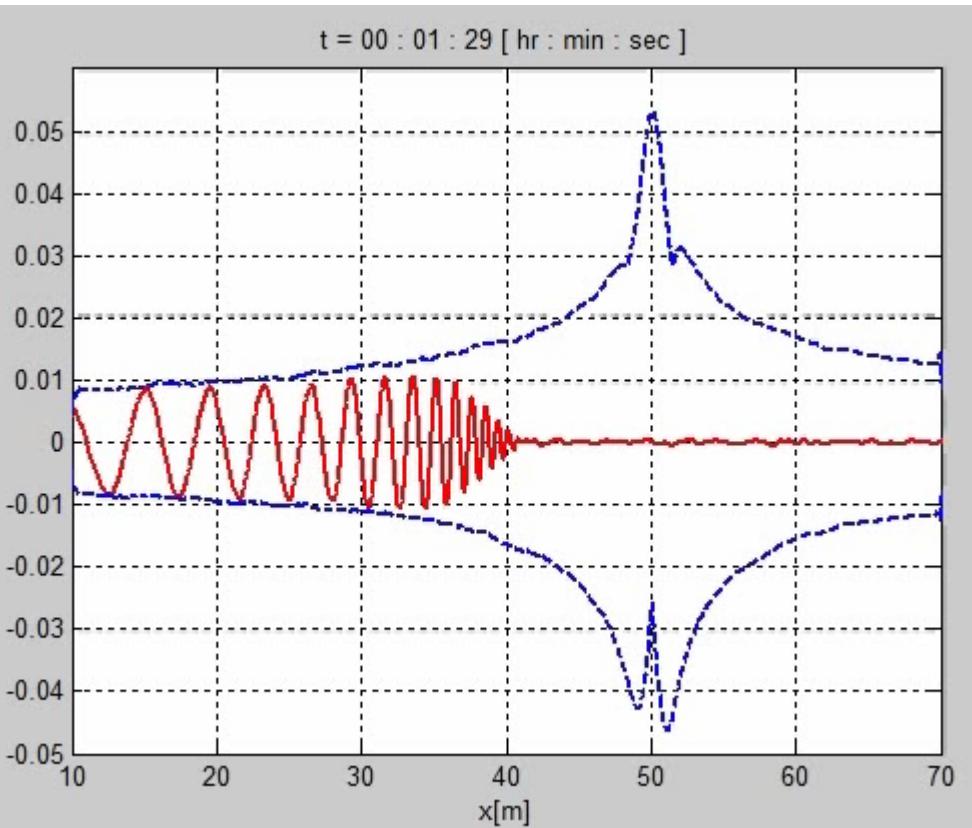
LINEAR SIMULATIONS



Linear compared to nonlinear:

- earlier in time: 20[s], shorter distance 140[m] (group velocity)
- crest height 0.9m lower, through 0.08 m less deep

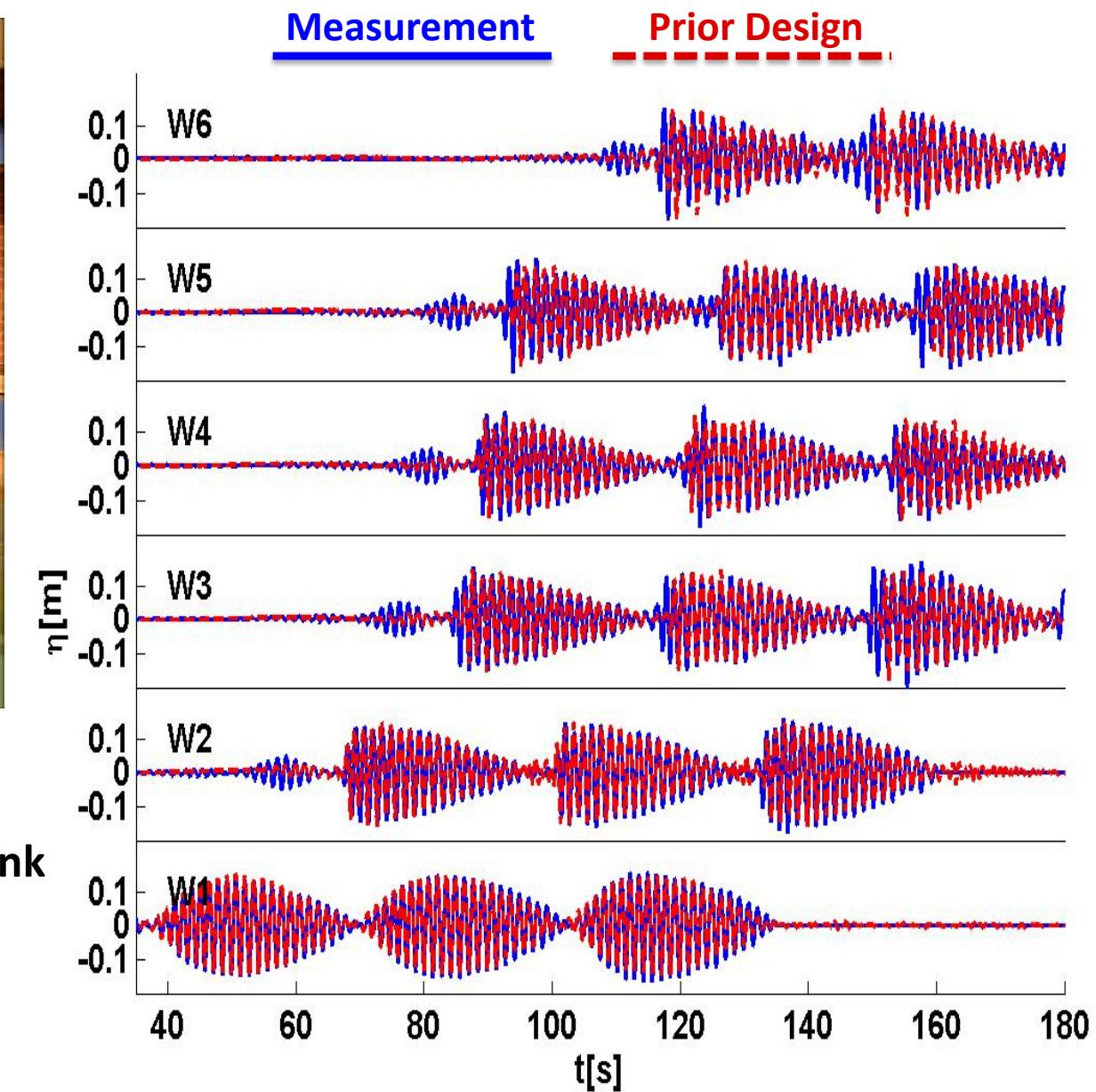
Wave Focussing



Design and pre-calculation experiment TUD wave tank



Bichromatic wave breaking, $k.a=0.3$, at TU-Delft towing tank

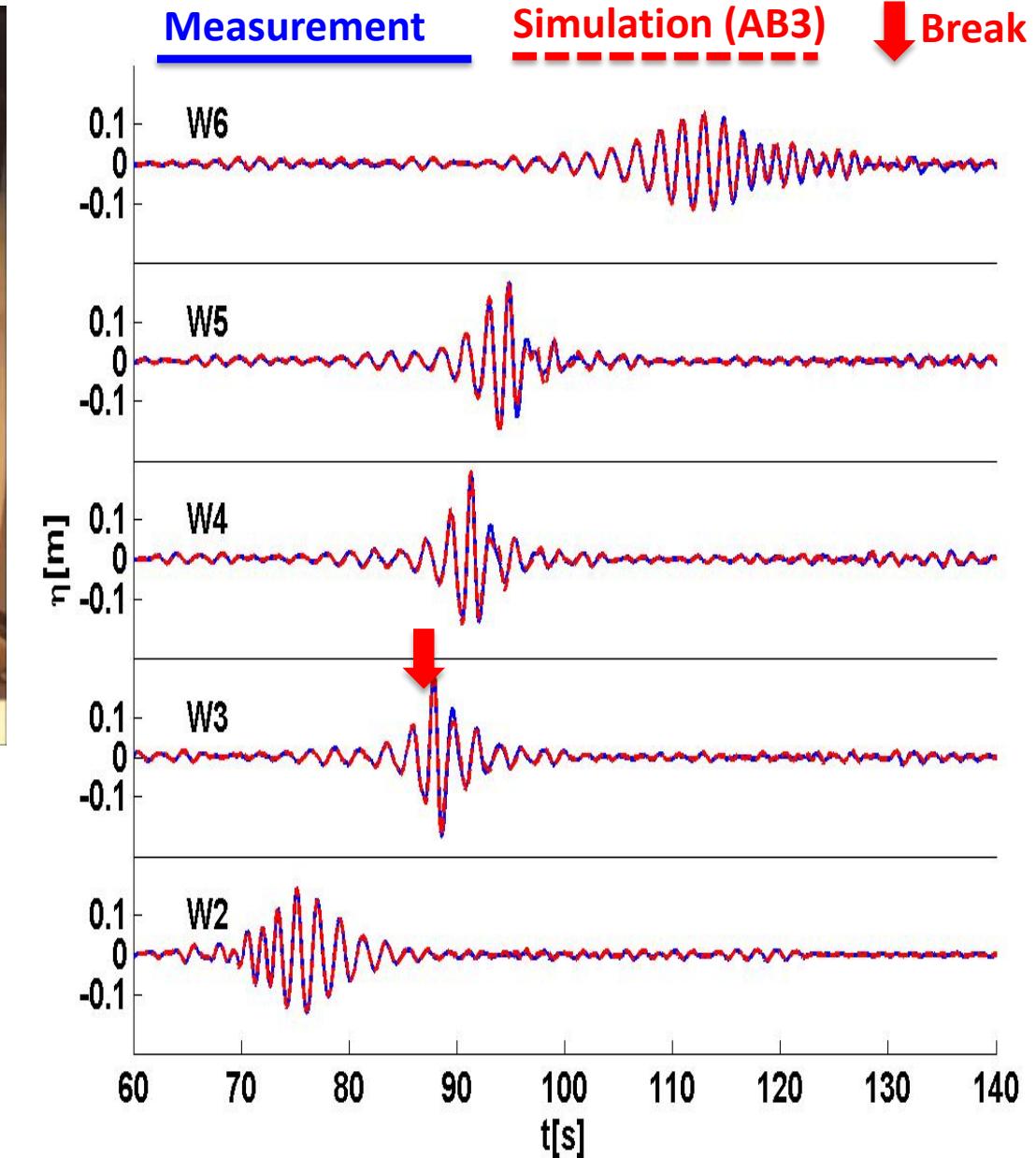


Wave breaking



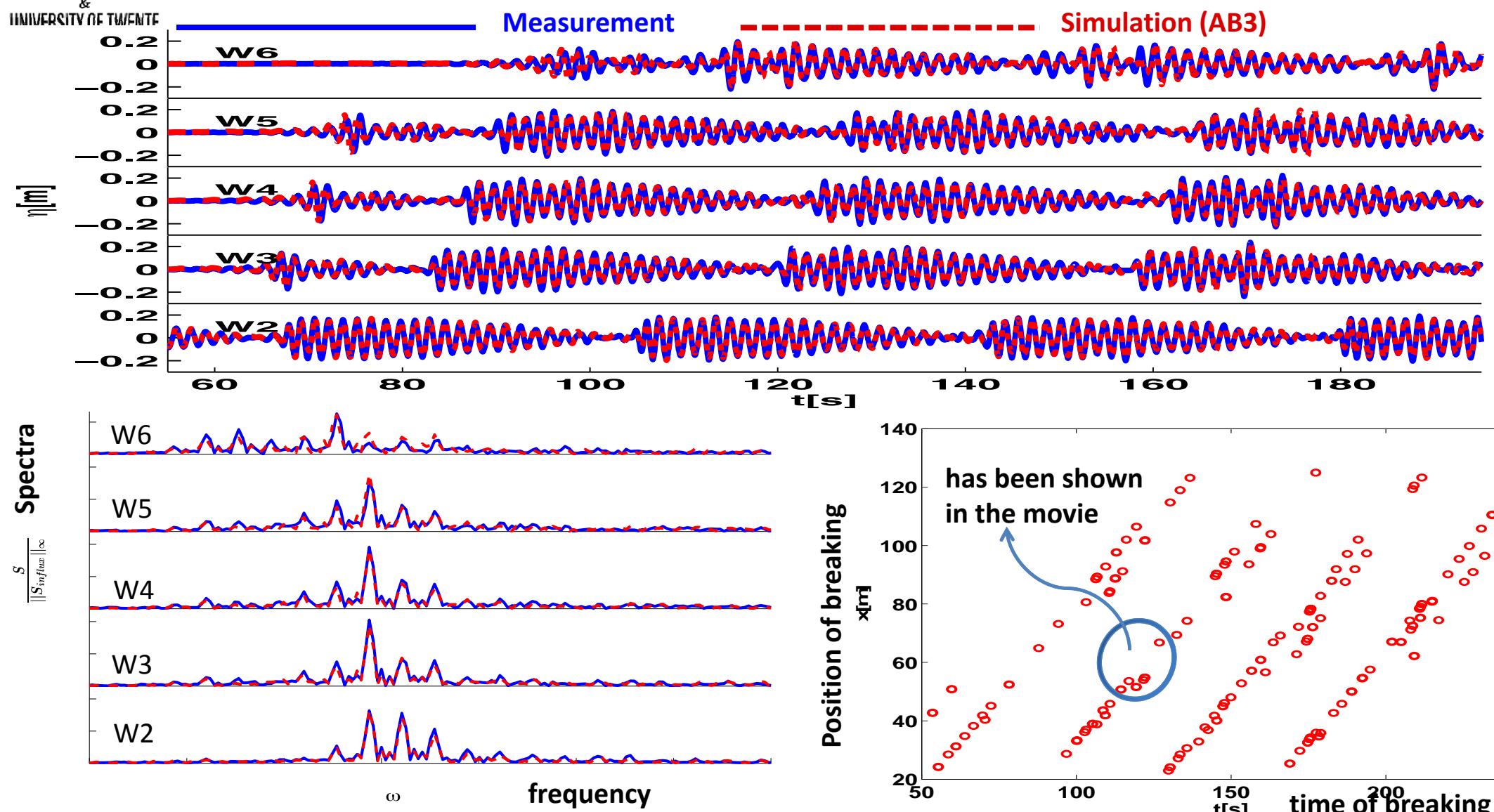
Focussing $k_p \cdot a = 0.11$

TUD1403Foc7



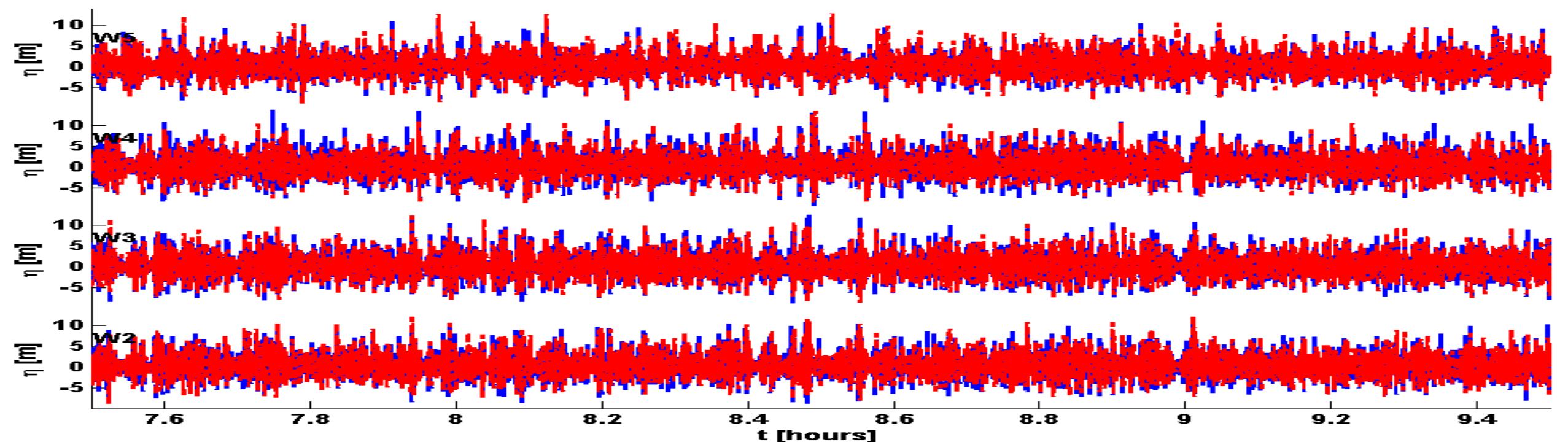
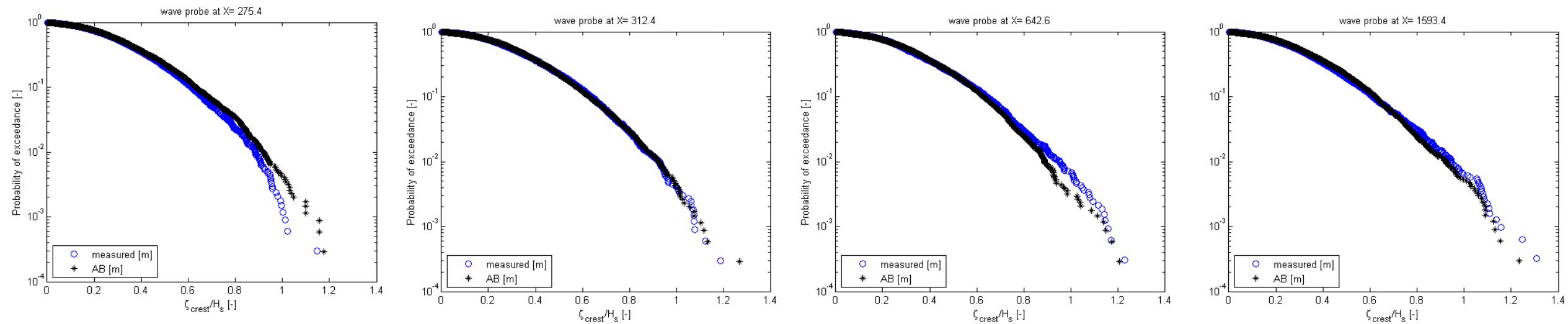
Bichromatic wave $k_p.a=0.37$

Wave breaking

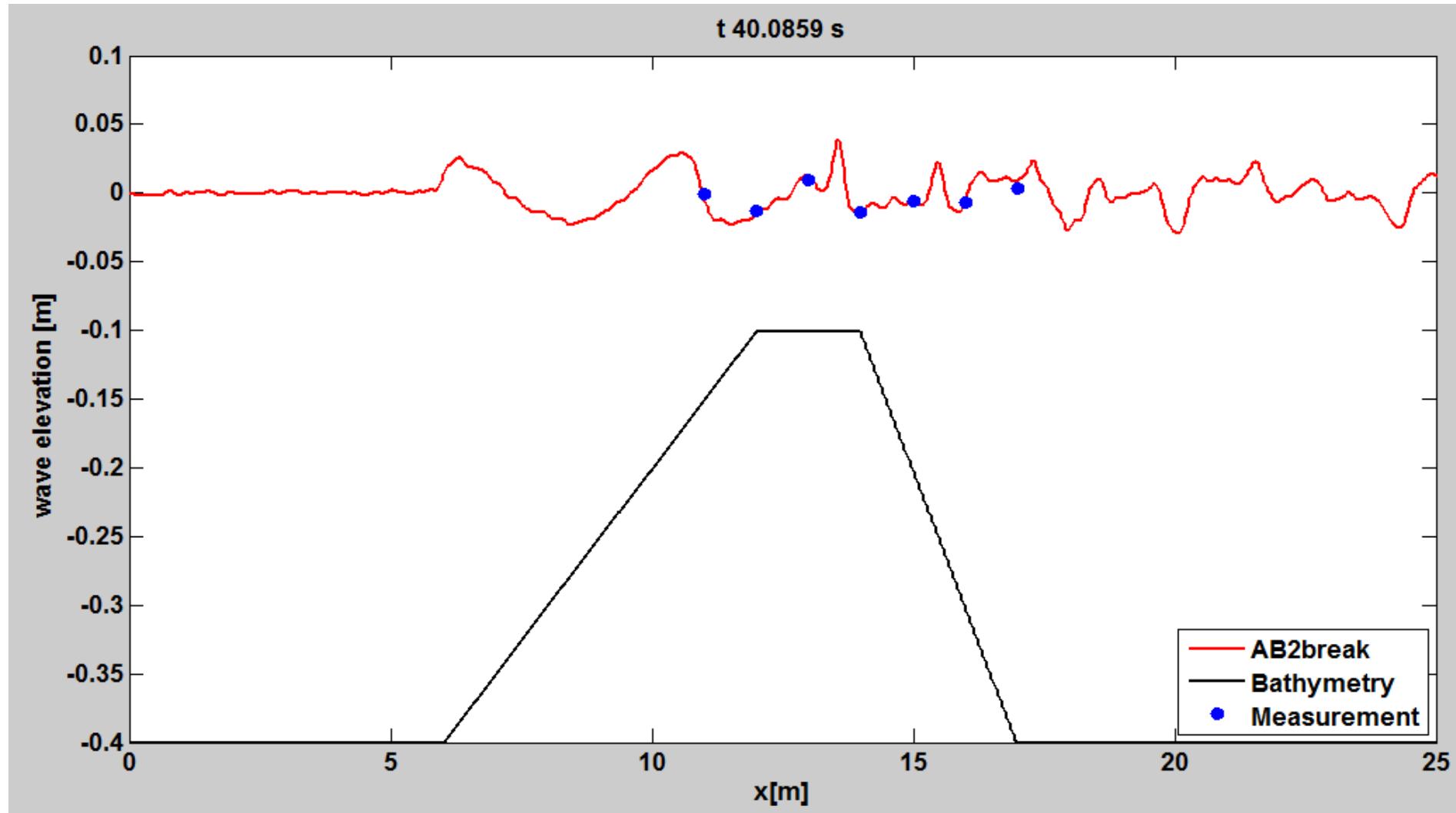


CREST JIP 223002F (MARIN)
Tp:12 S (Breaking), 9hrs ; Crel≈1.5

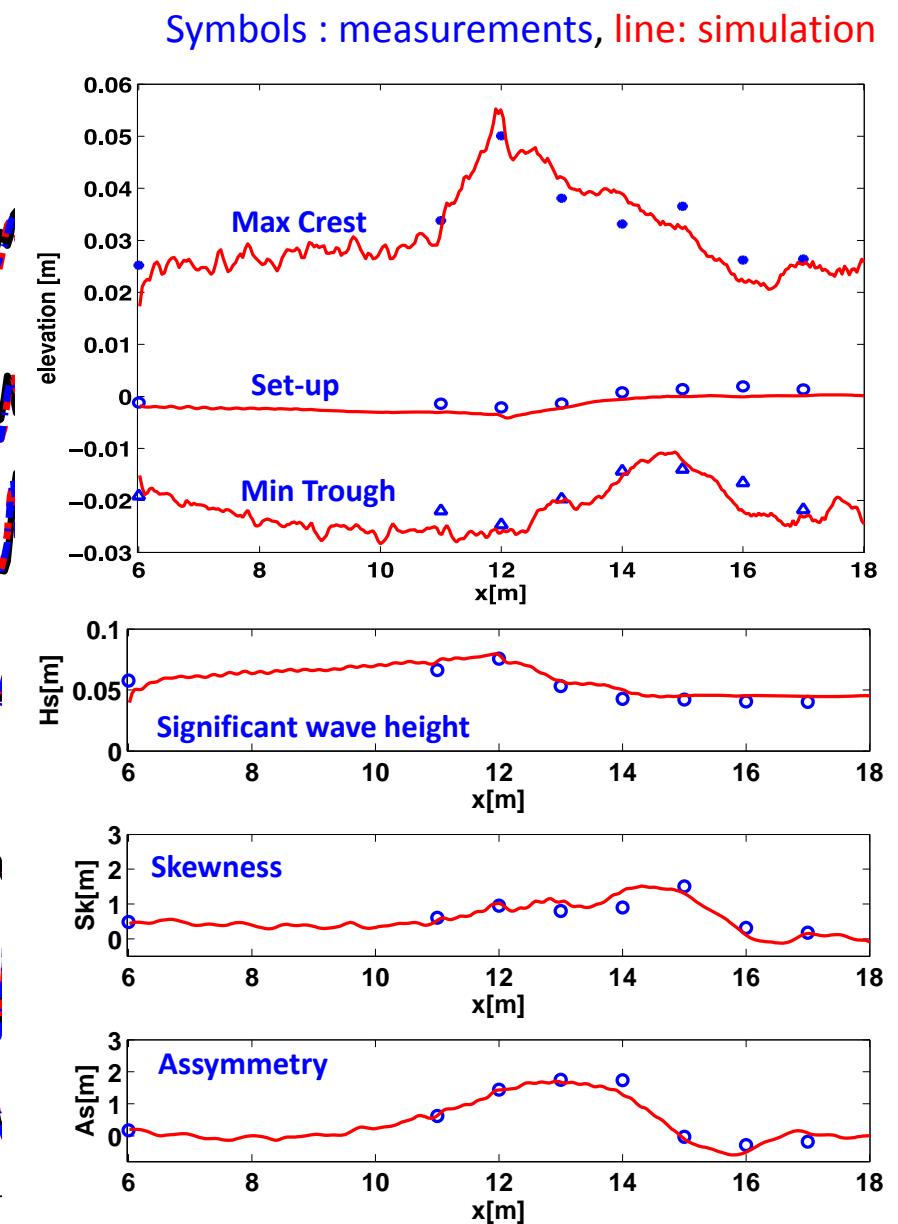
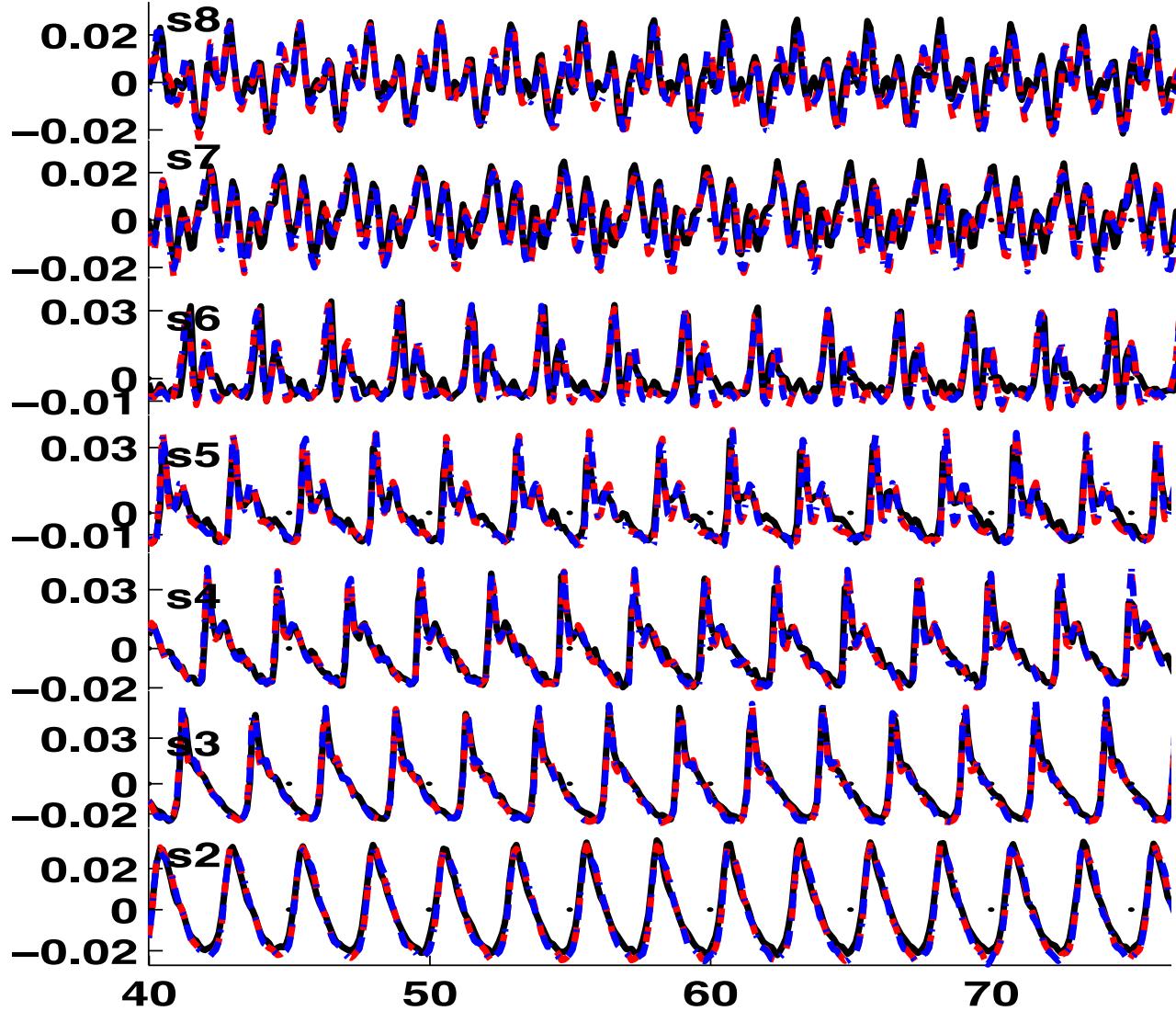
Exceedance plots for breaking waves



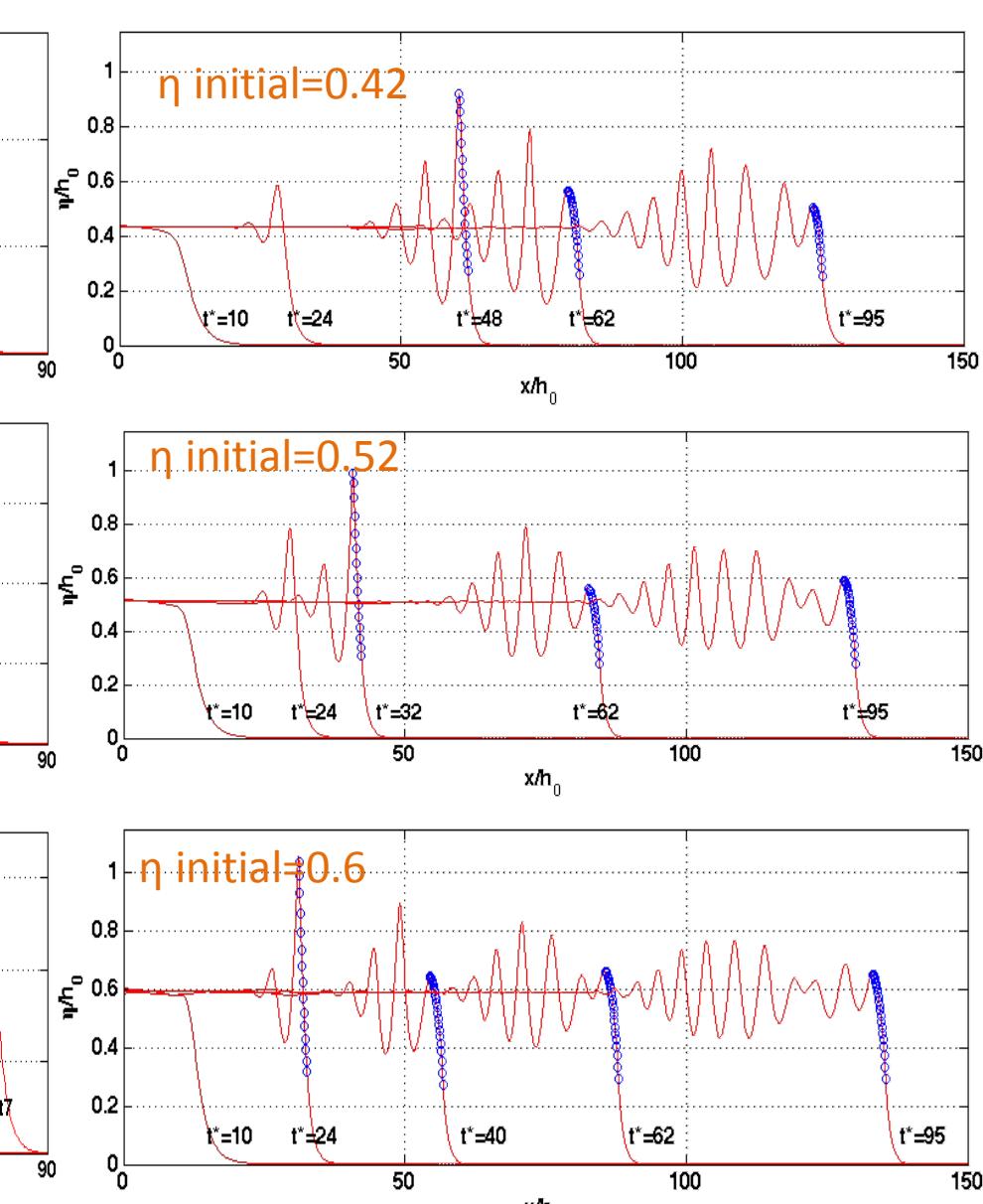
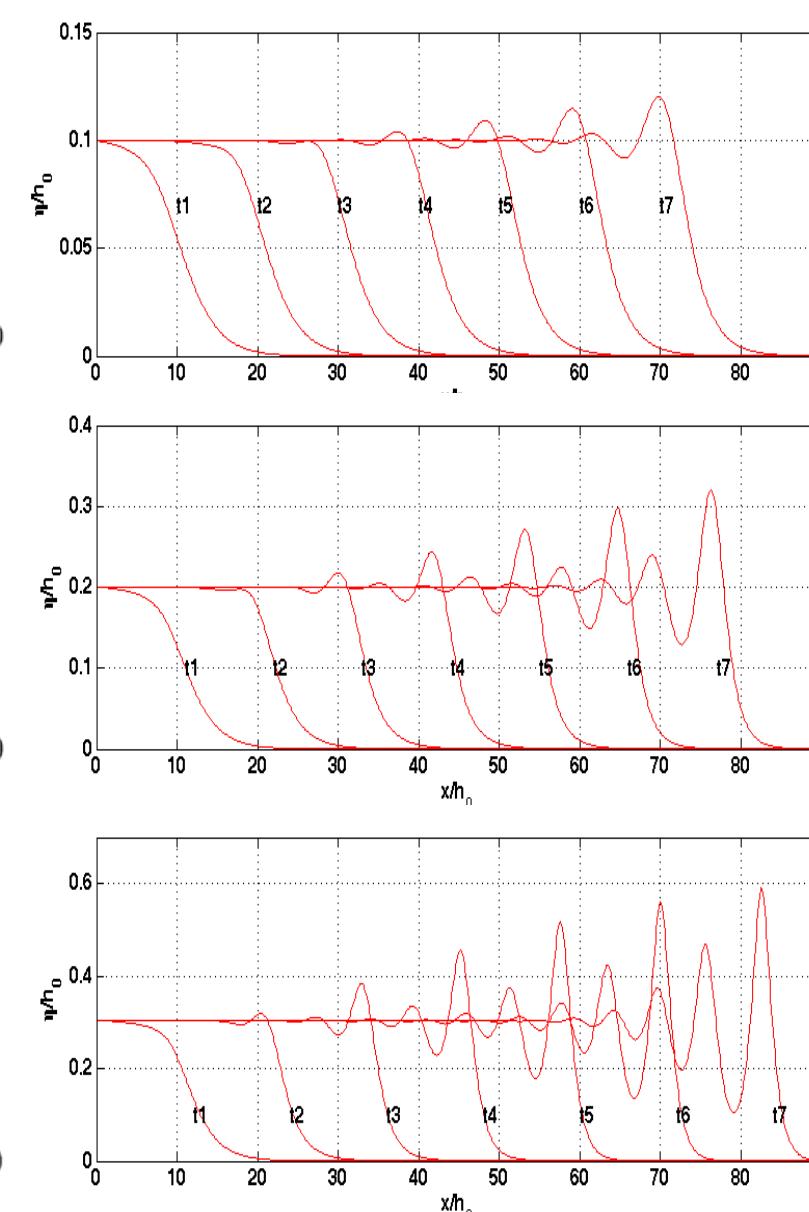
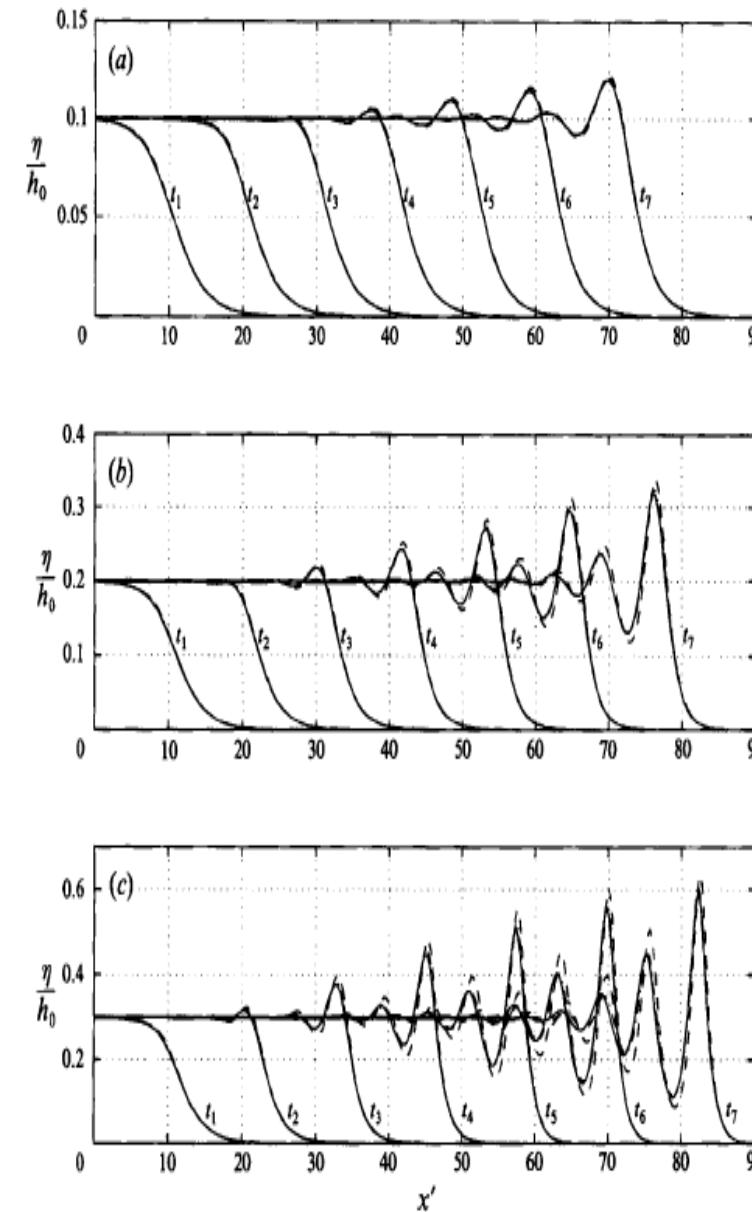
Bound Harmonic Generation Phenomenon (Wave Decomposition)



Beji and Battjes Experiment (1993) : Periodic Wave Plunging Breakers case ($f=0.4$ Hz)



Transition from undular to purely breaking bore

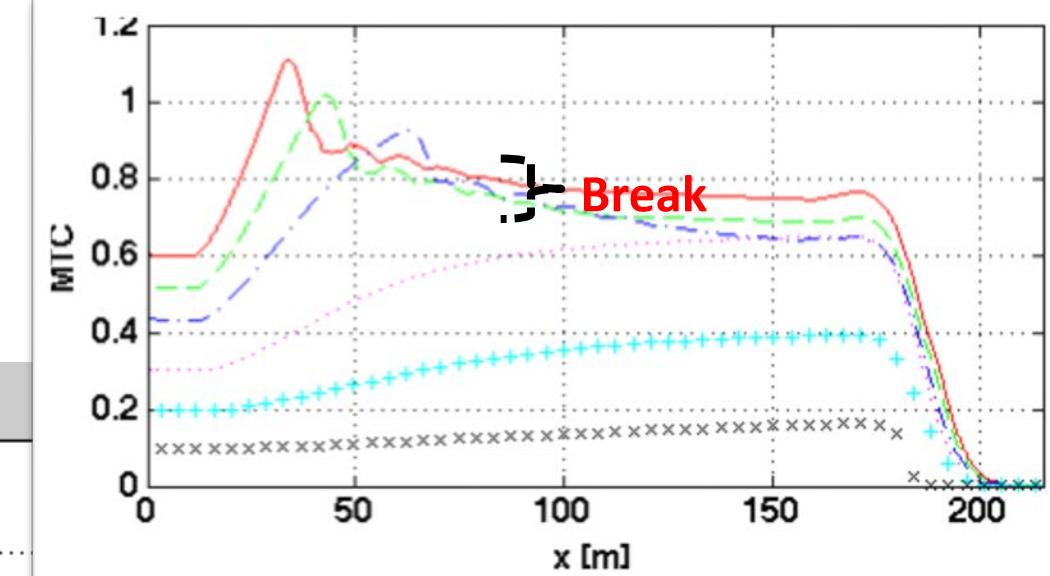
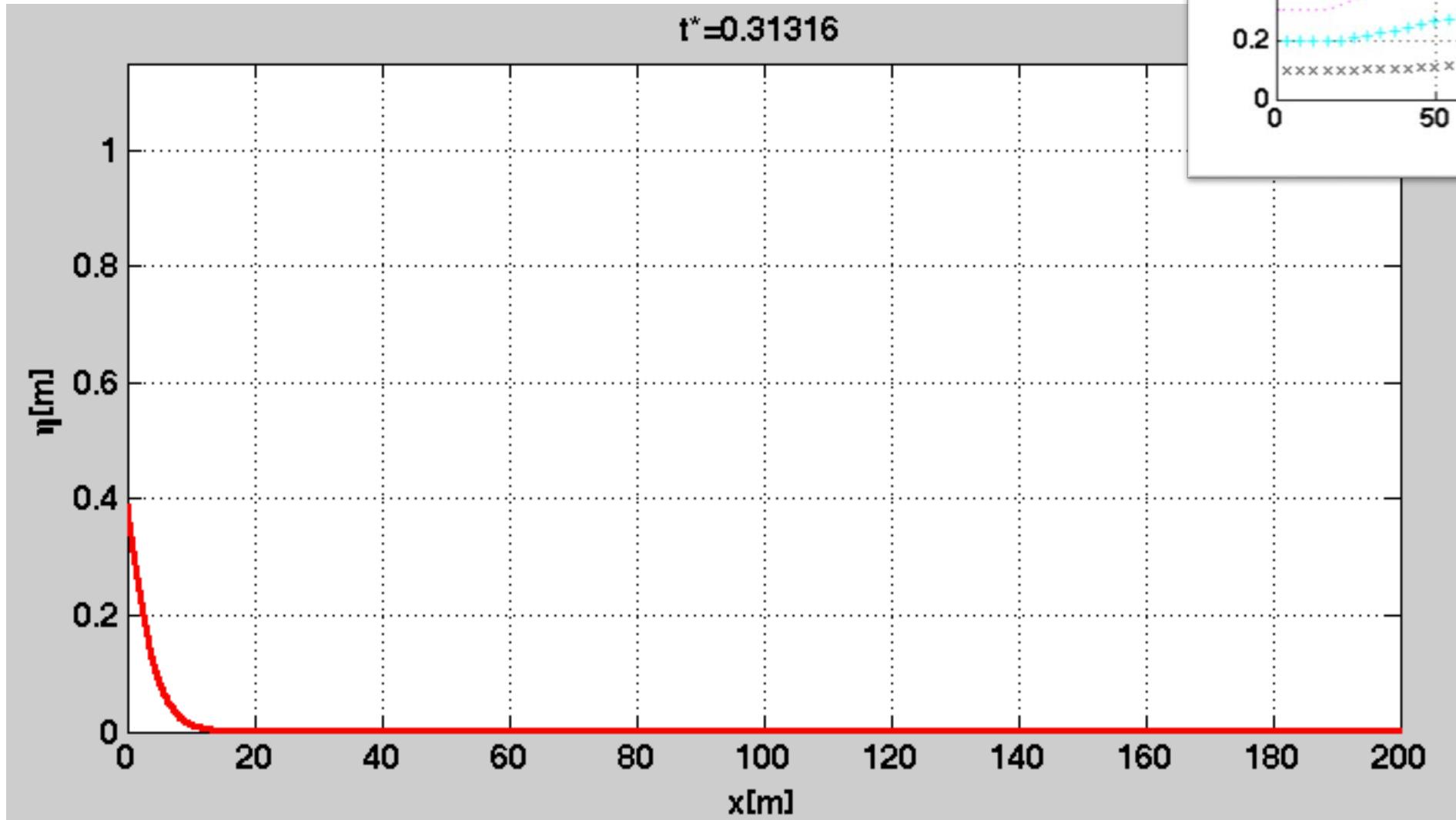


Simulation using fully nonlinear potential flow (Grilli, et al)

Non breaking case

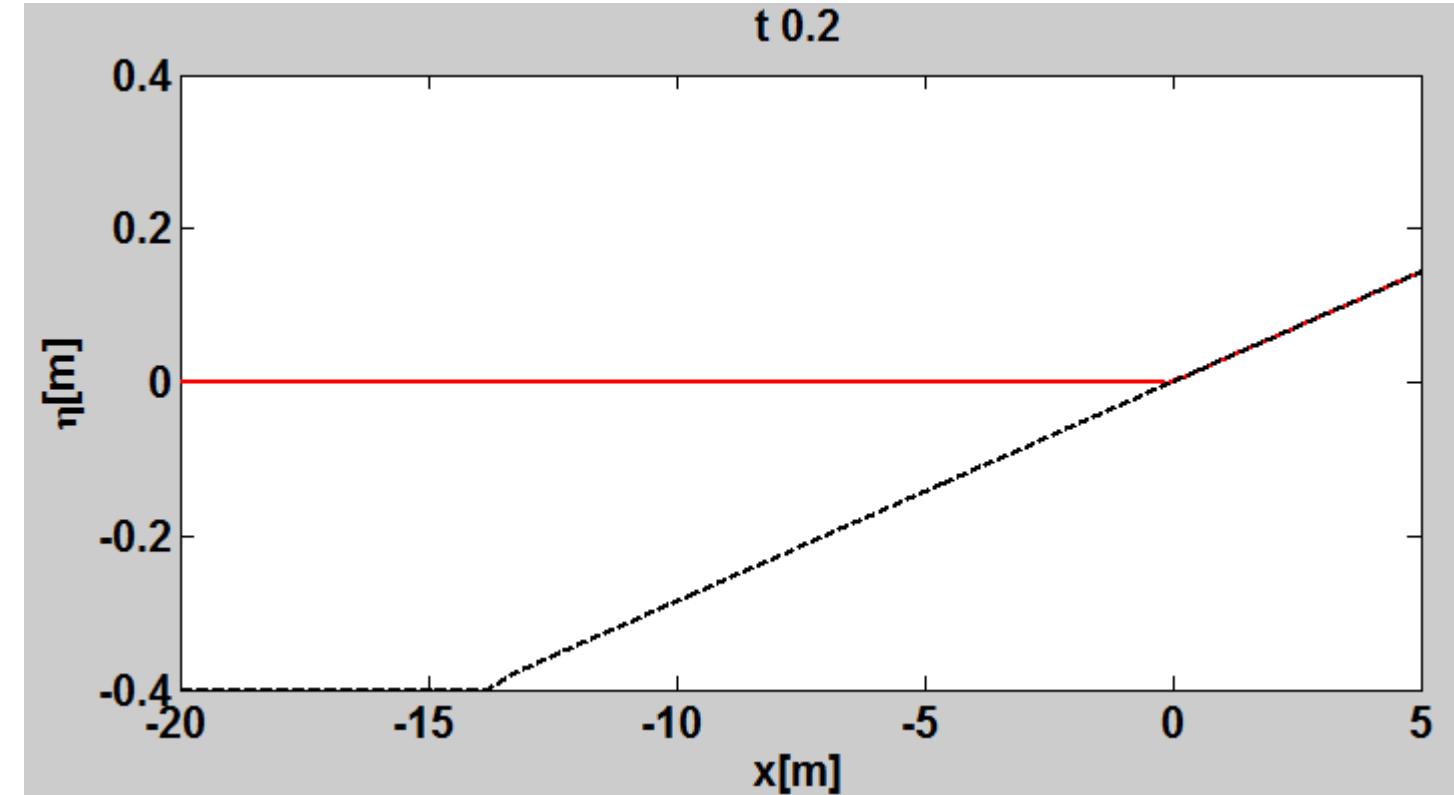
Simulation using AB

breaking case



Spilling wave breaking above a slope (Exp. Ting & Kirby 1994)

 elevation
 Breaking nodes

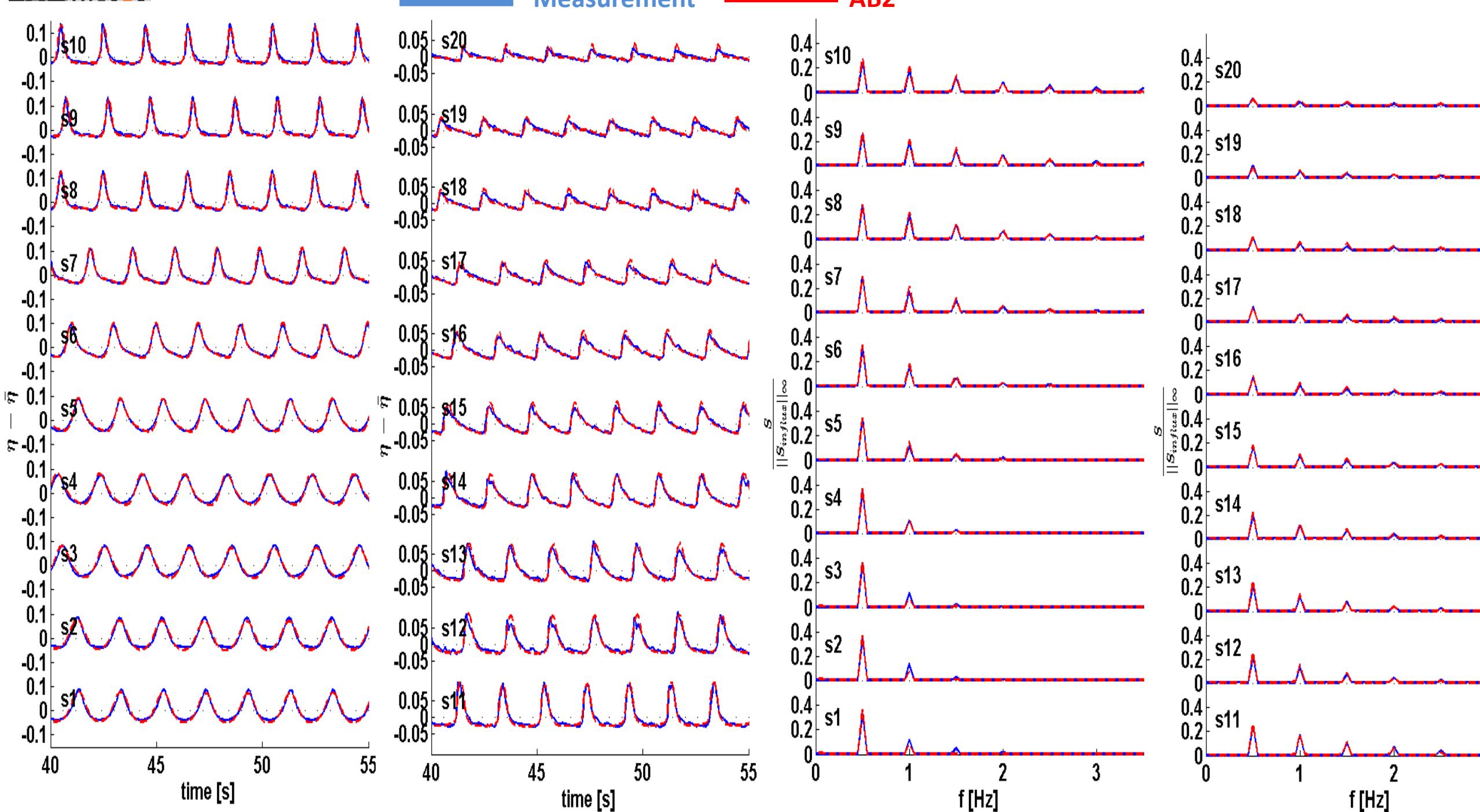


Correlation

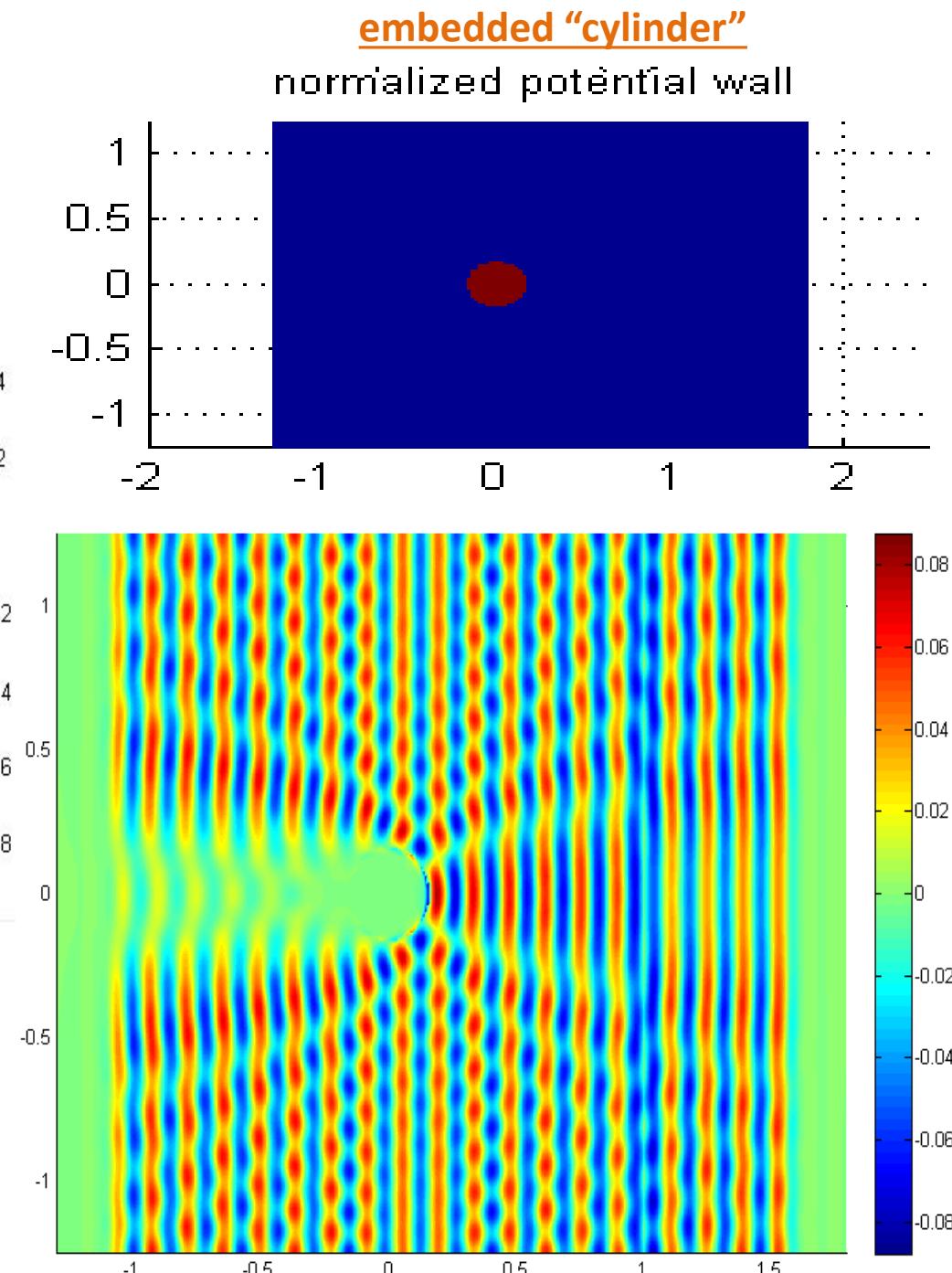
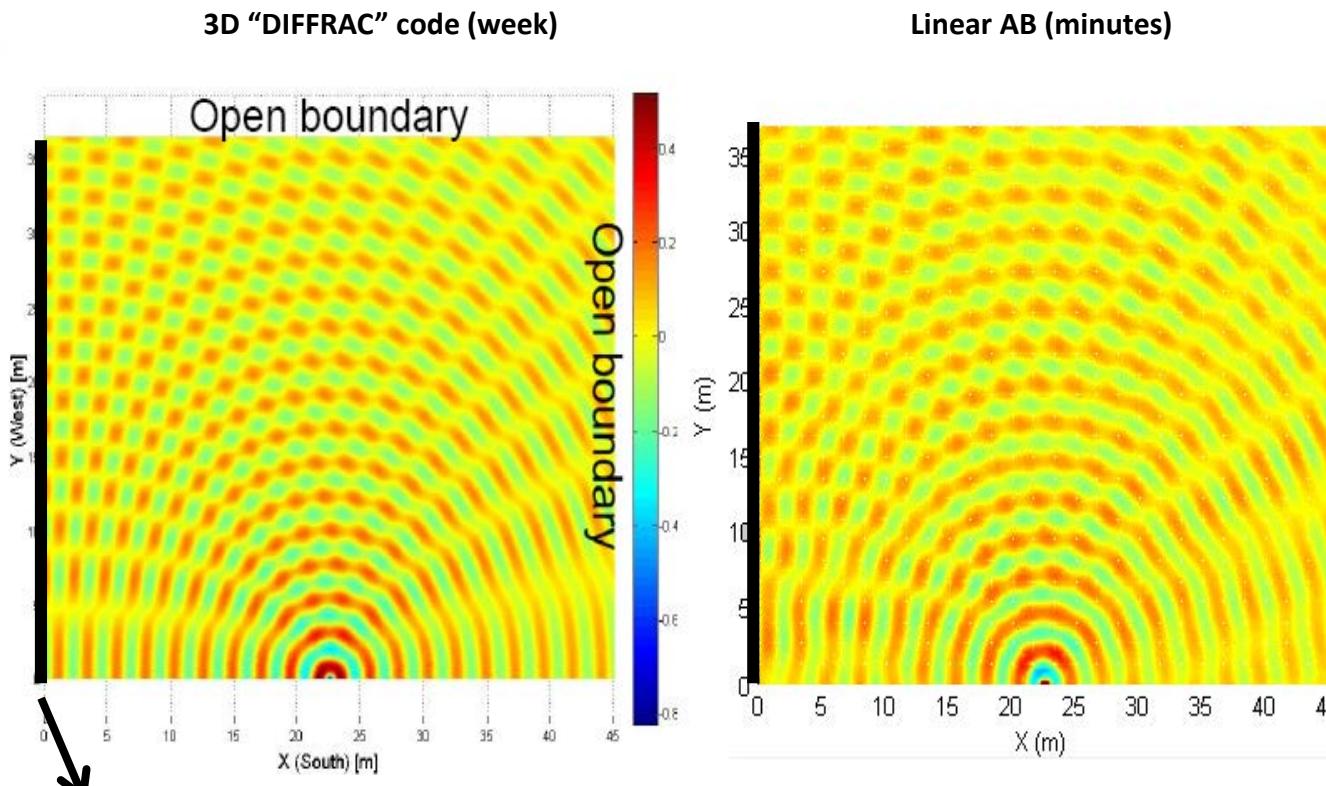
s1	s2	s3	s4	s5	s6	s7	s8	s9	s10
0,97	0,97	0,98	0,98	0,99	0,95	0,97	0,98	0,98	0,95
s11	s12	s13	s14	s15	s16	s17	s18	s19	s20
0,96	0,96	0,97	0,97	0,96	0,94	0,94	0,91	0,91	0,84

$C_{rel} \approx 35 \rightarrow \approx 5$ for simulation time 60 s :

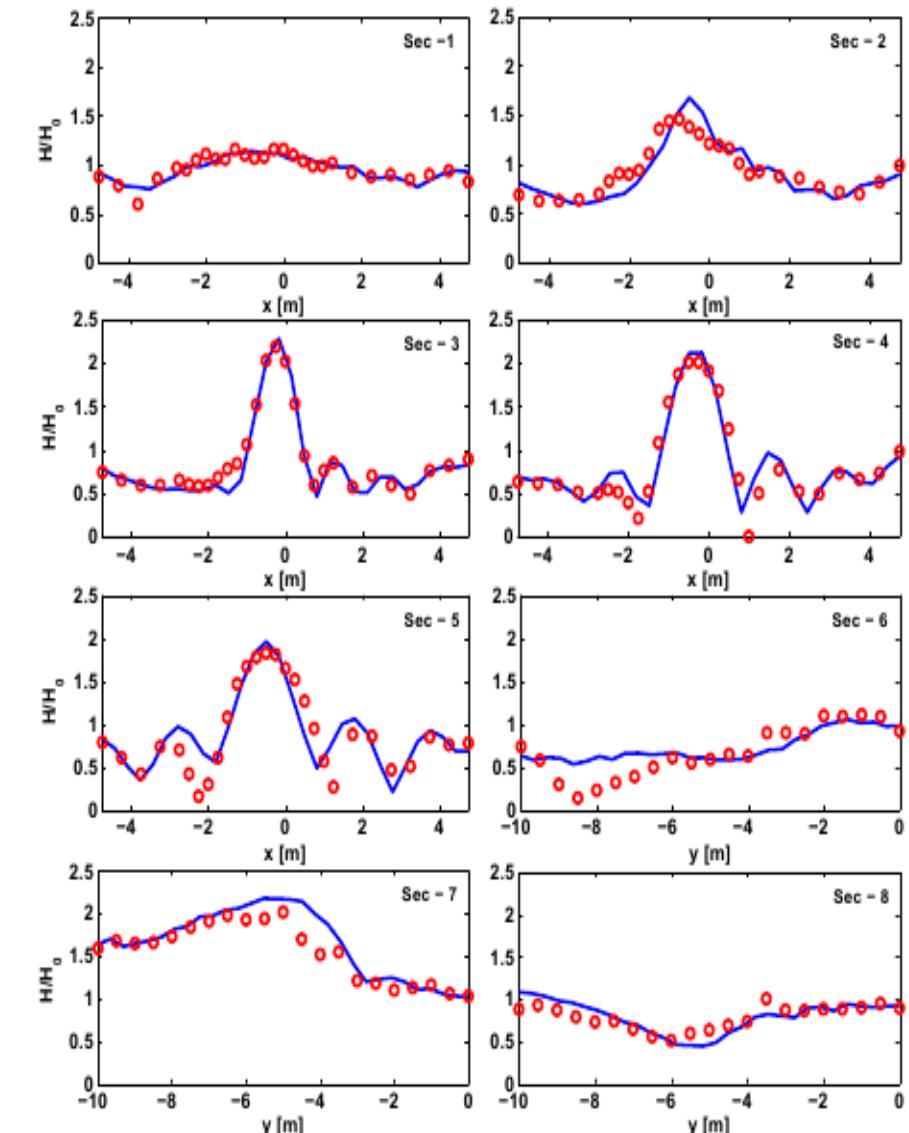
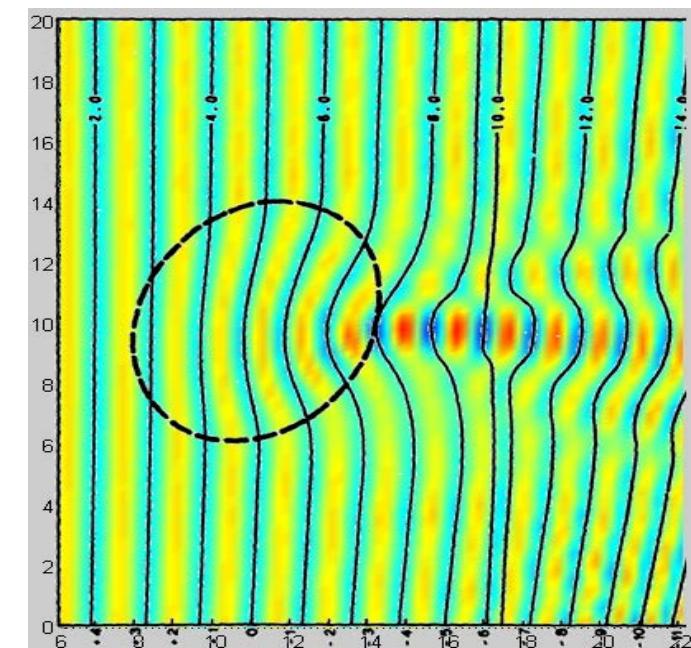
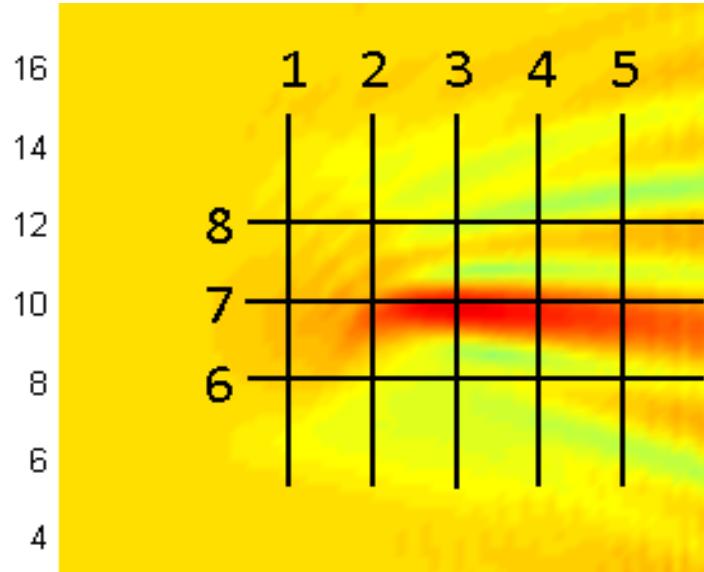
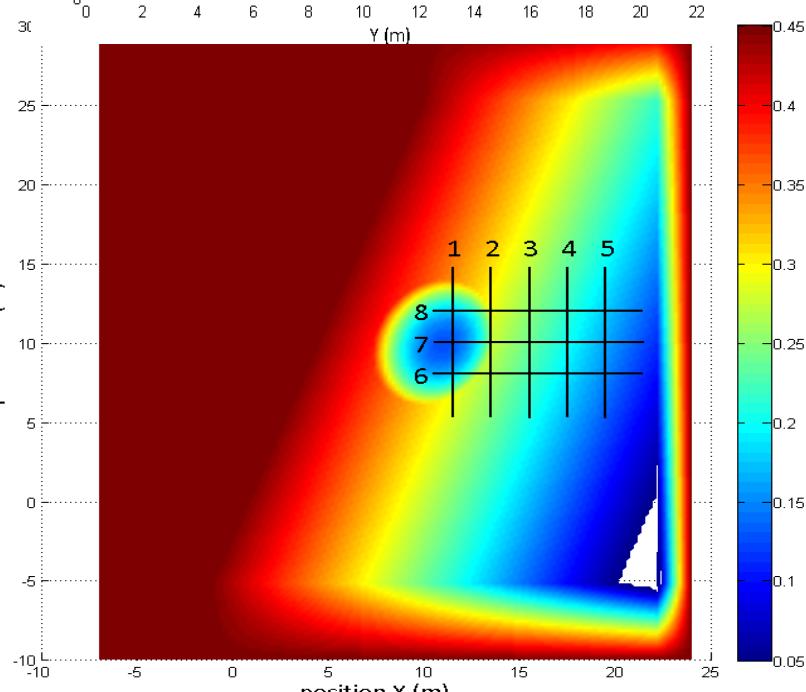
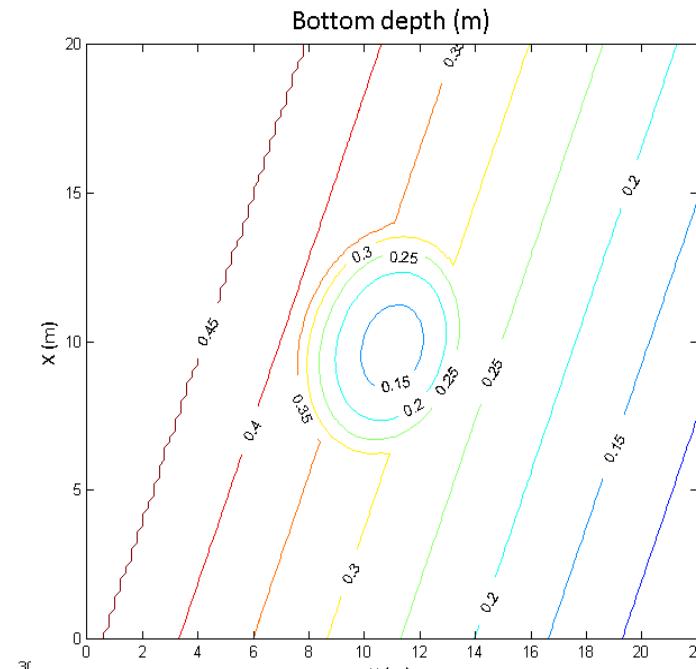
- multiple breaking continue over 5 period.
- small spatial discretization (170 points per wavelength)

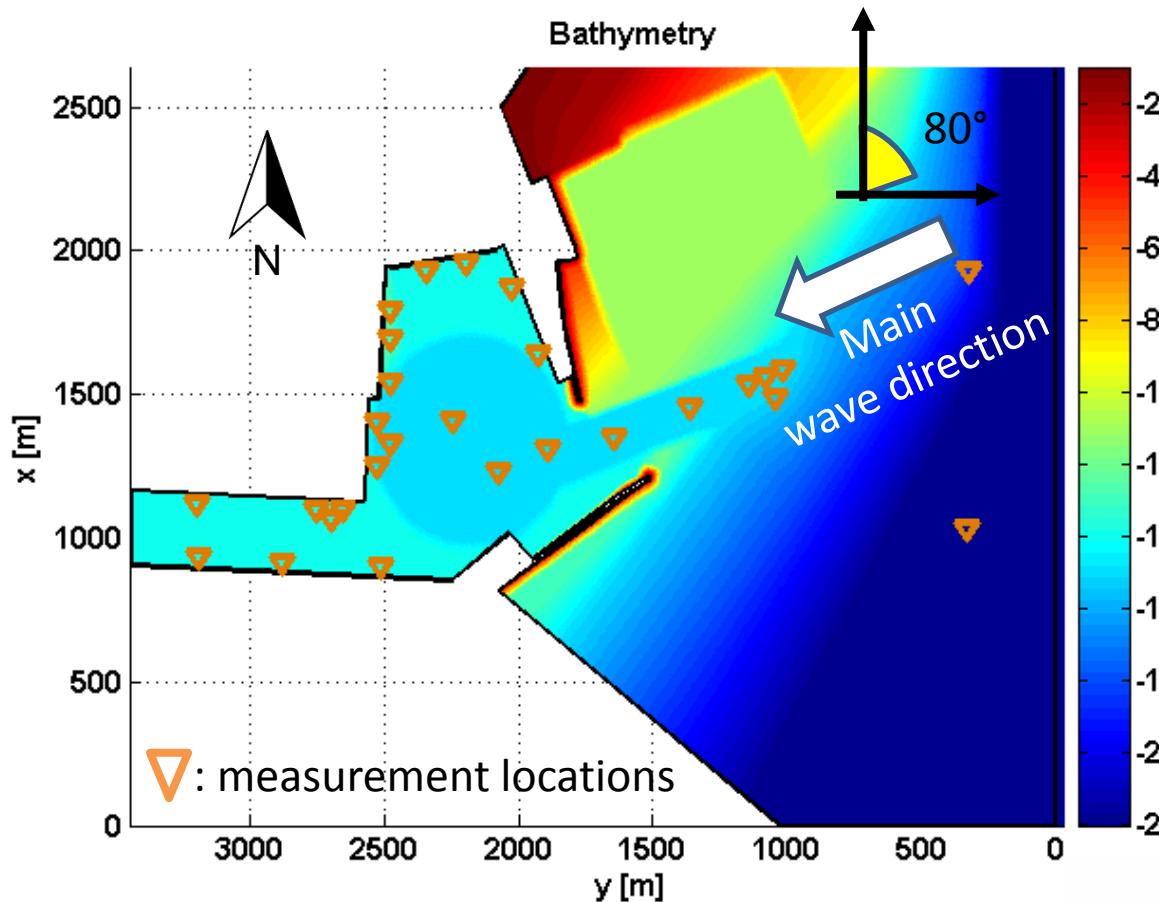


Embedded reflective interfaces 2D



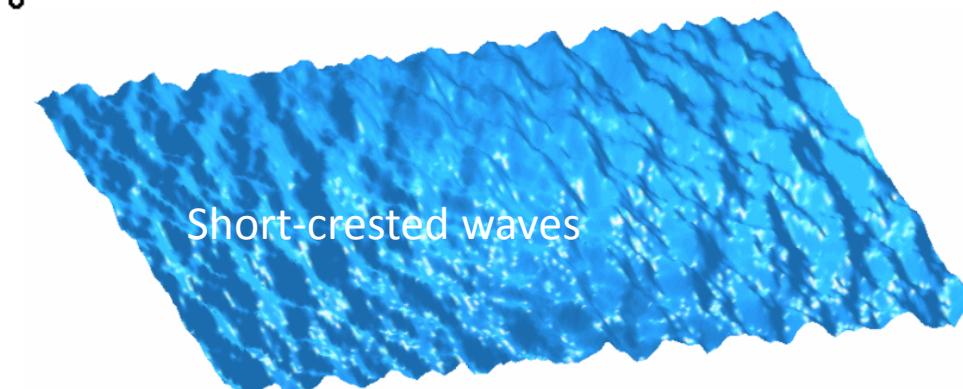
2HD Refraction & Diffraction (Berkhoff 1982)





Wind wave – input :

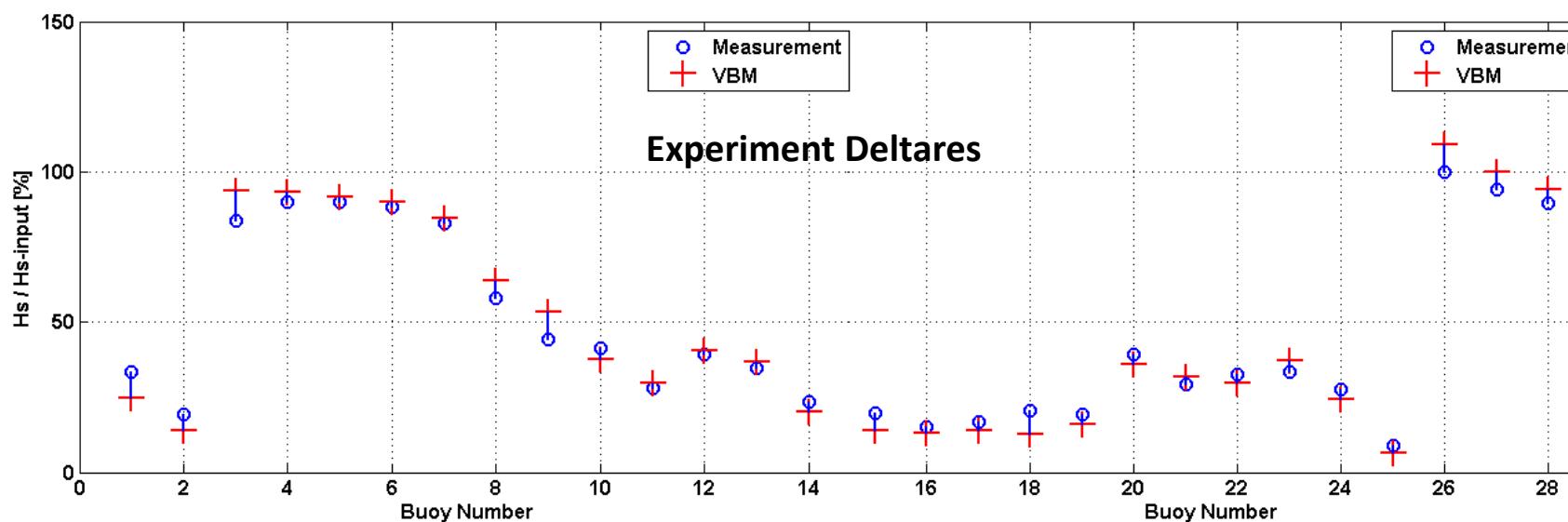
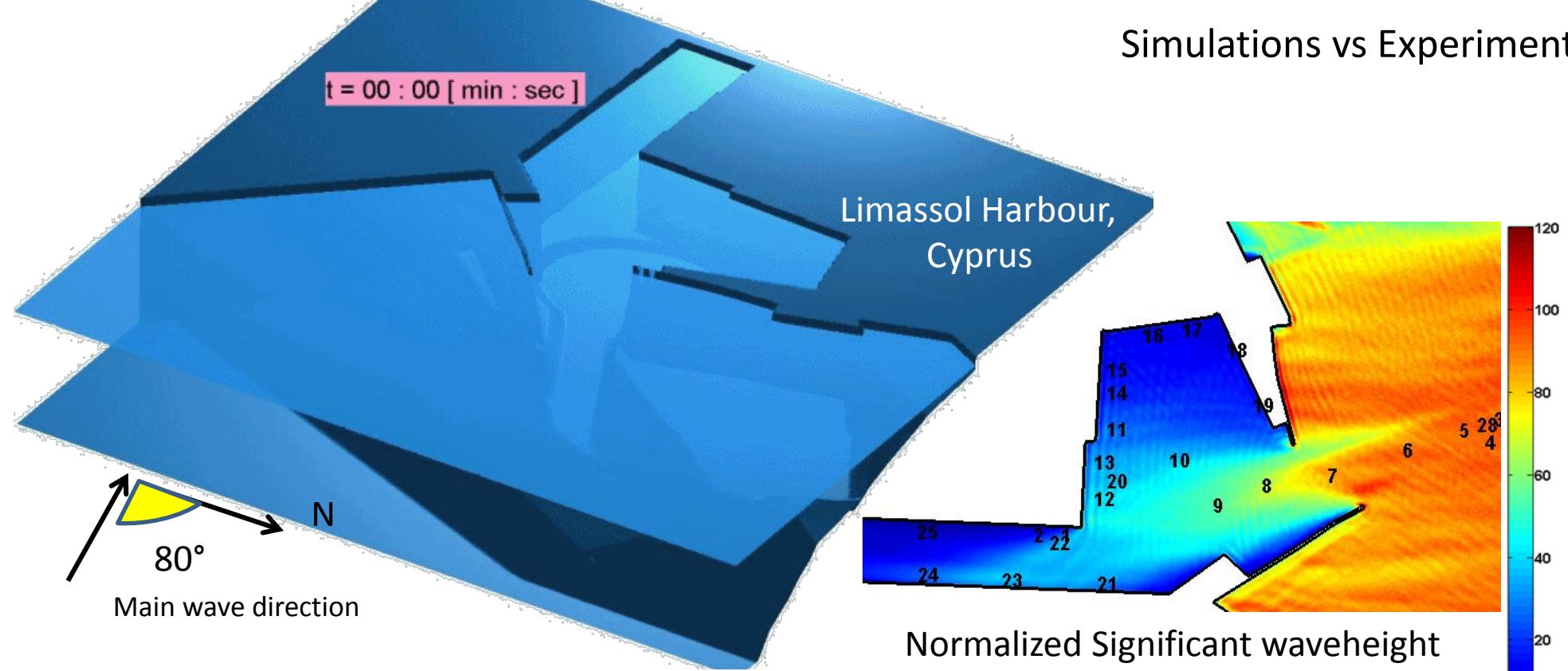
$H_s = 2.5 \text{ m}$
 $T_p = 7.0 \text{ s}$
 Direction = 80°
 Short-crested waves



Experiment by Deltires 1992 :

- Complicated bathymetry
- Influx with **short-crested waves** (waves coming from various directions)
- Simulation of accurate harbour entrance

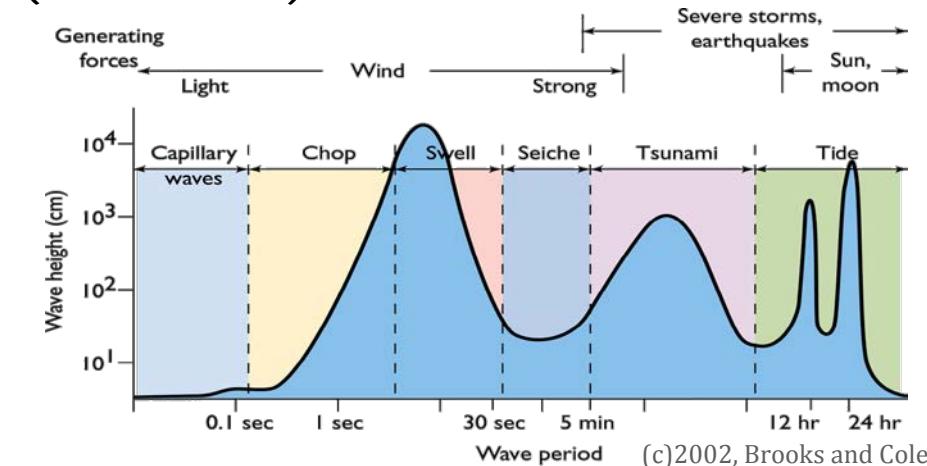
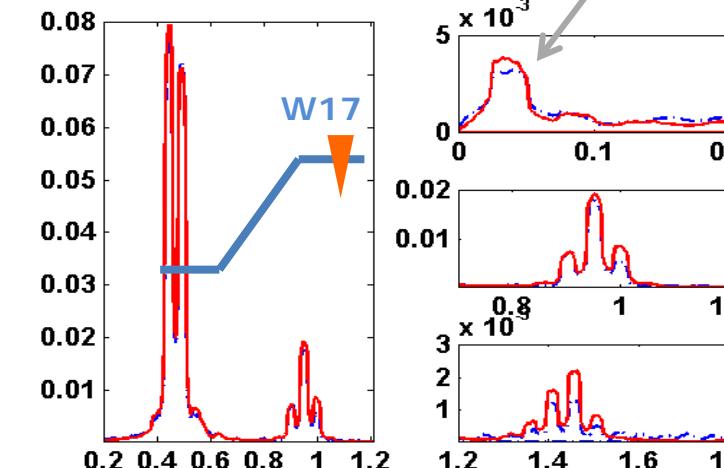
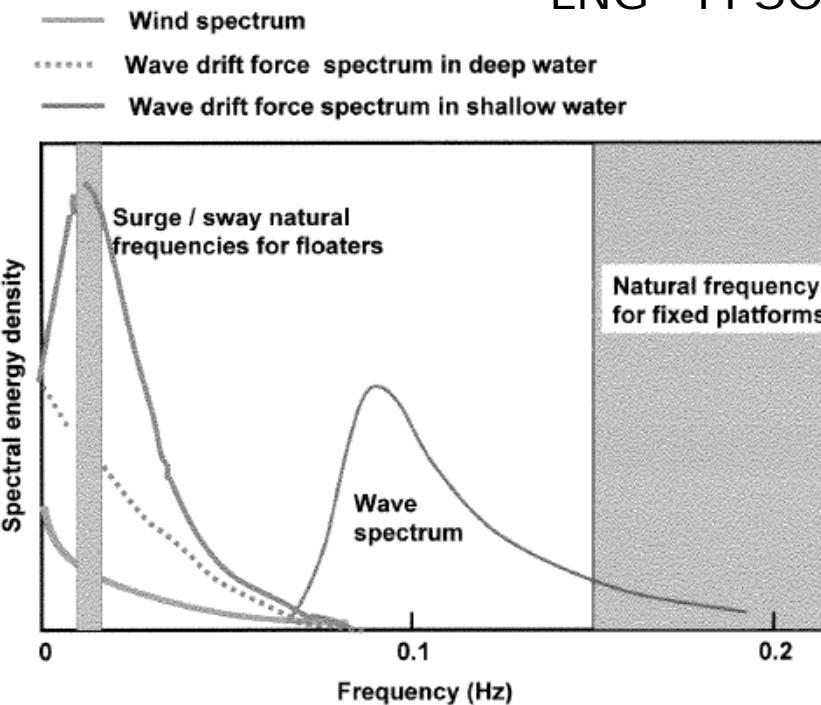
Simulations vs Experiments



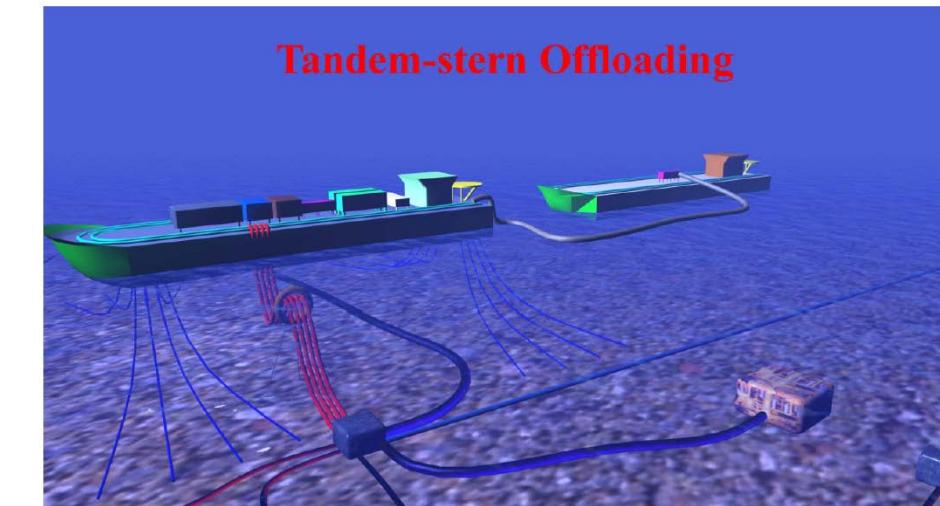
Application

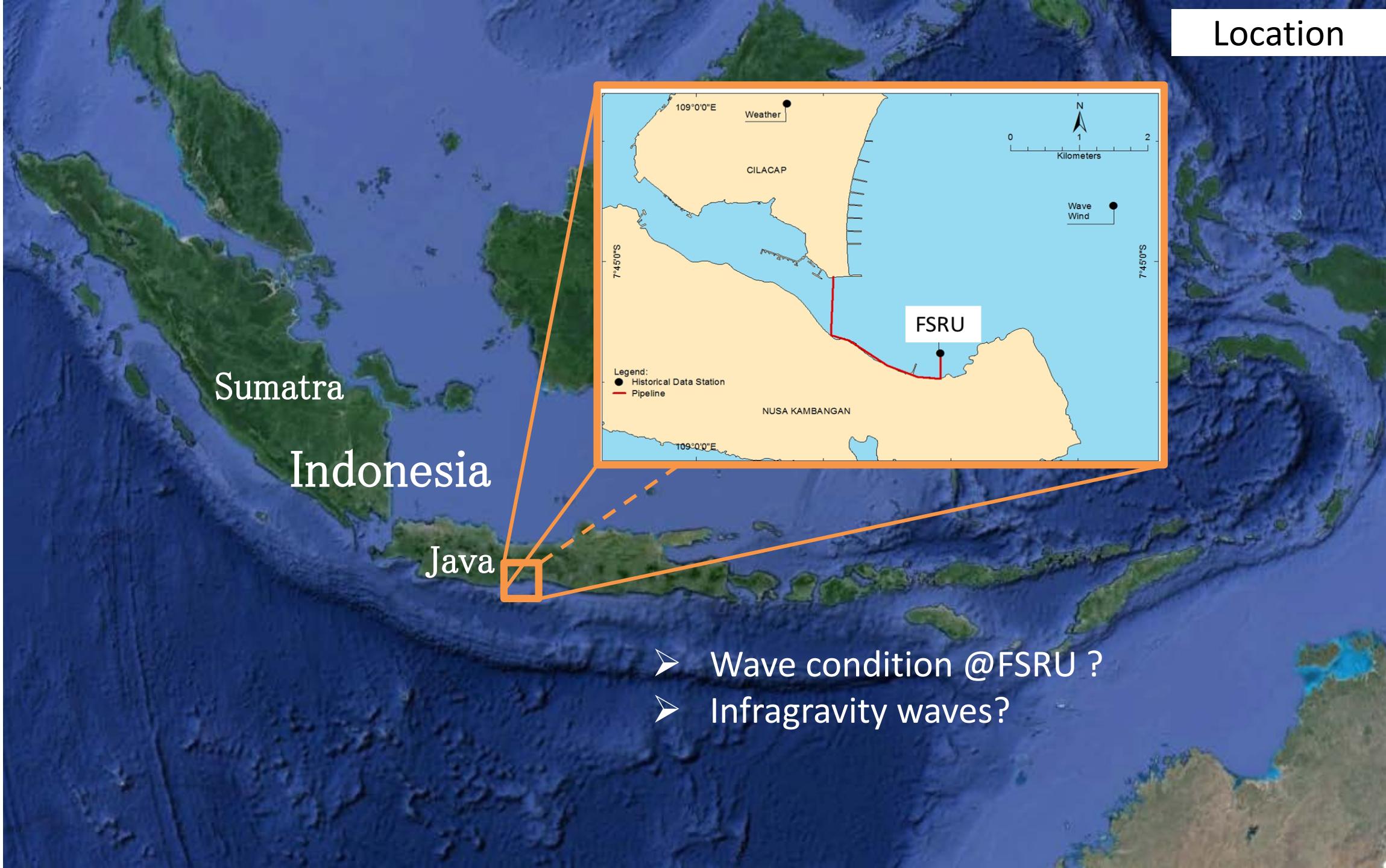
- Infra-Gravity calculation for gas-oil offshore industry, e.g.

LNG –FPSO operation sites (resonance)



**HaWAI'I bichrom
2 min Long.wave**



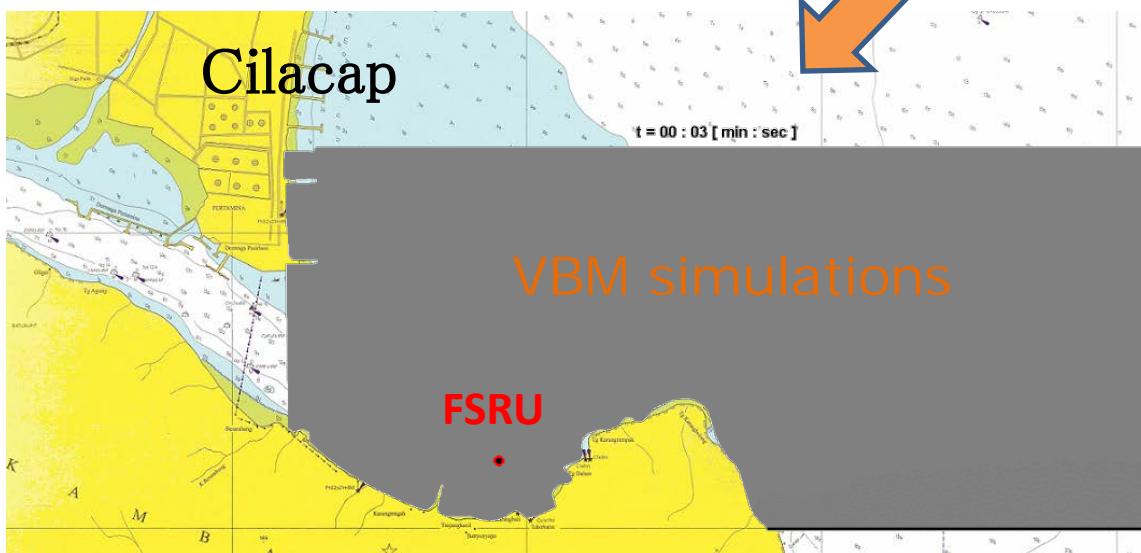
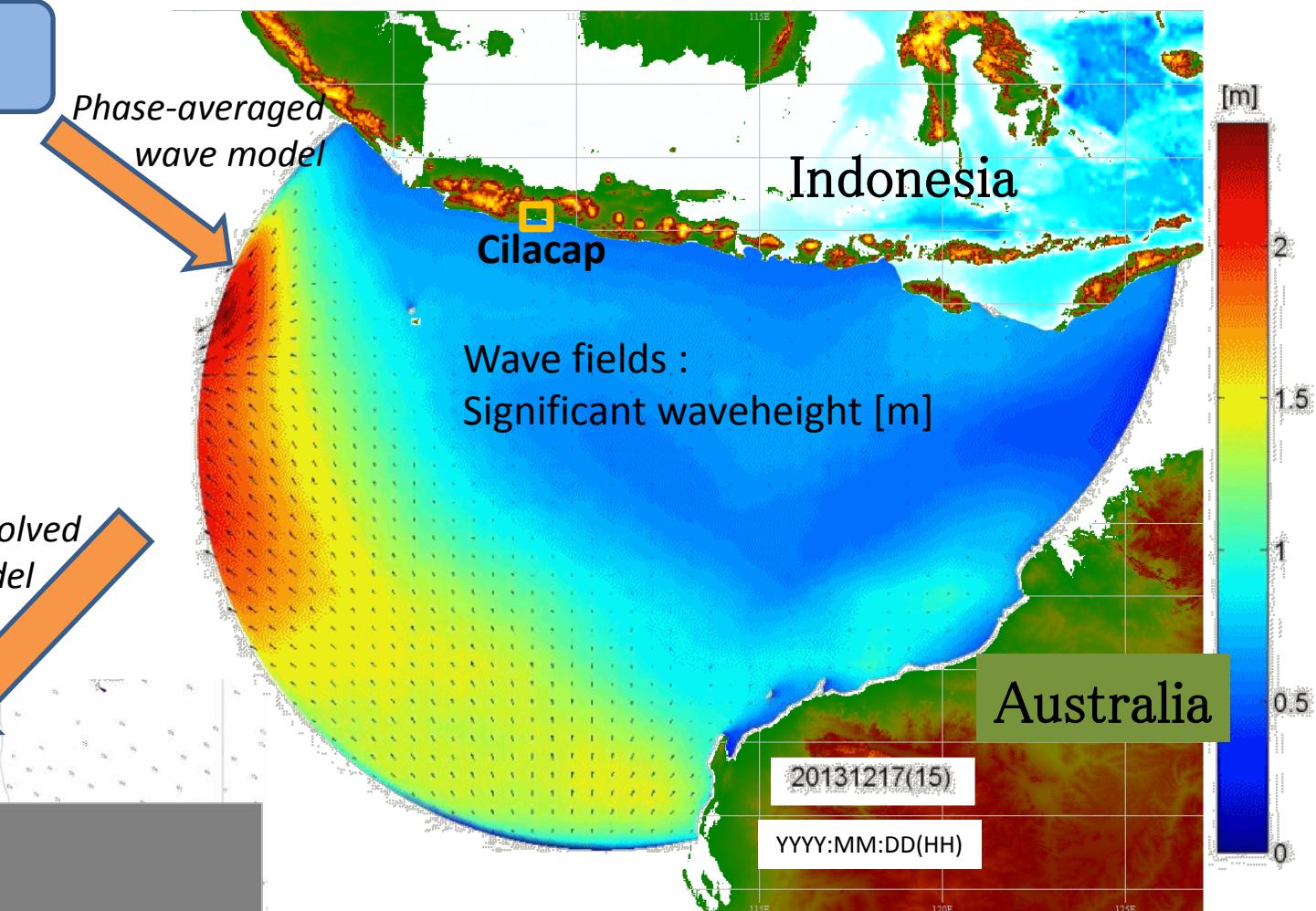


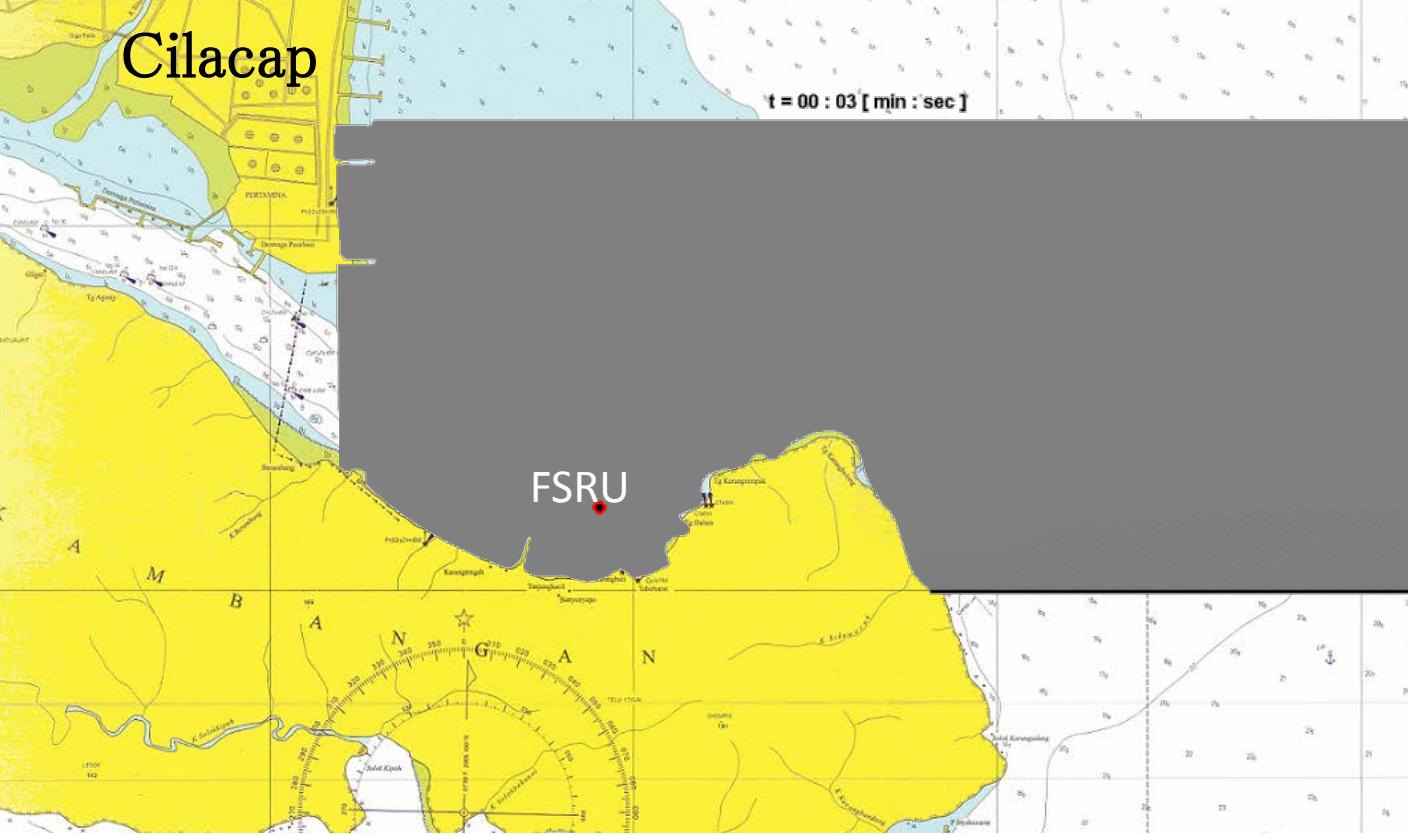
Simulations for Coastal Engineering applications

Wind field

Ocean waves generated by wind

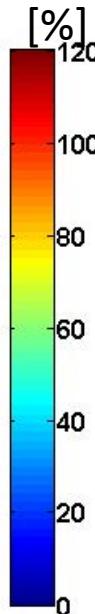
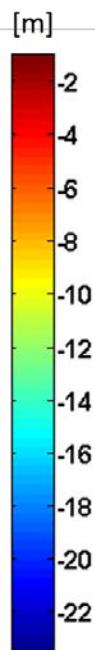
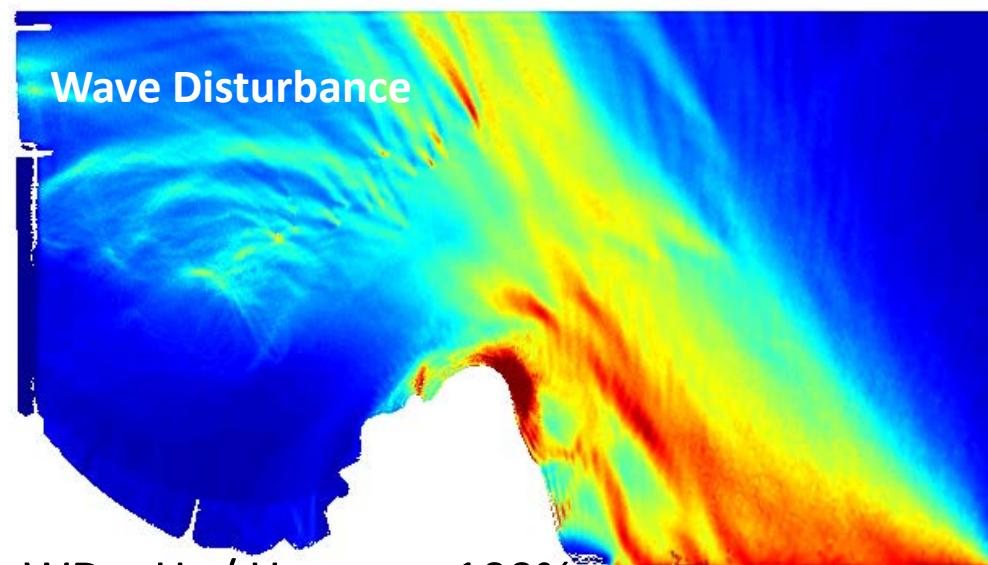
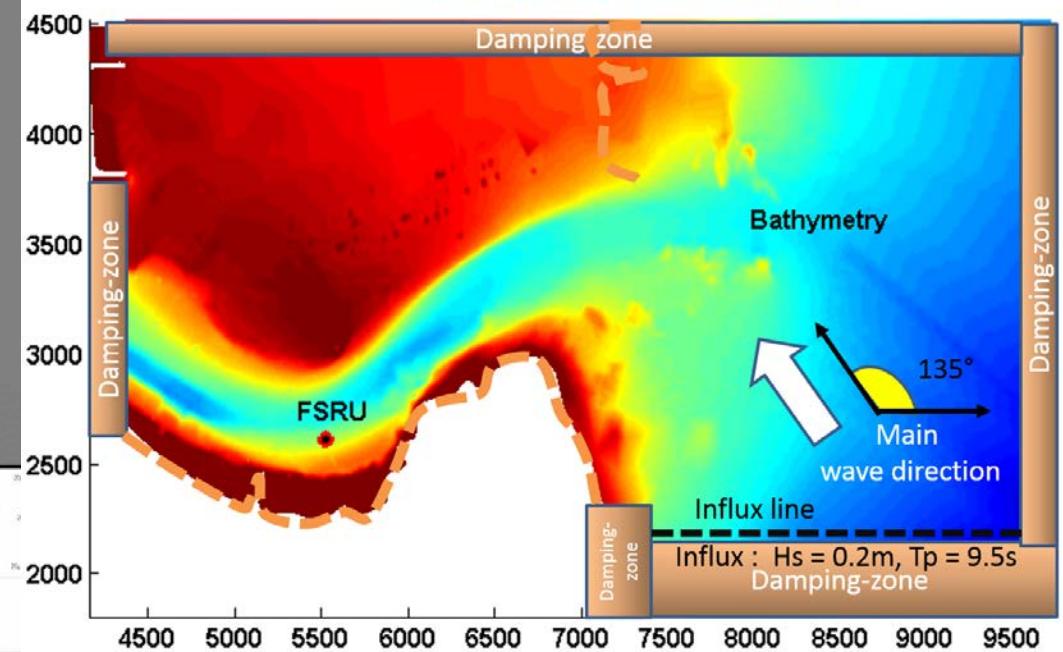
SWAN calculations produce 2D-spectrum
Design time trace of elevation heights at
numerical boundary for influx

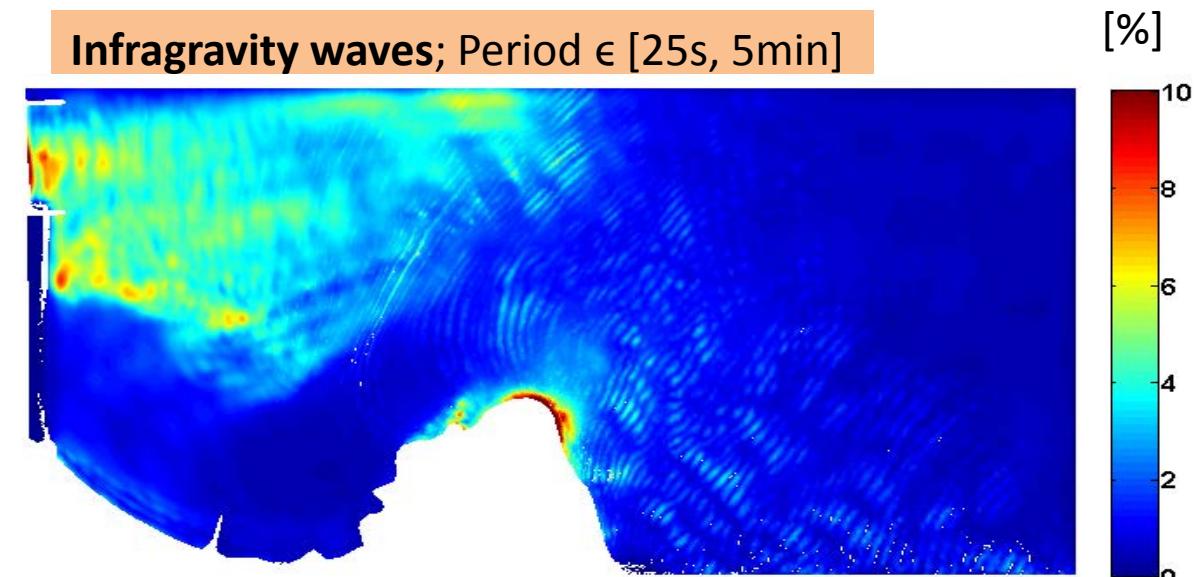
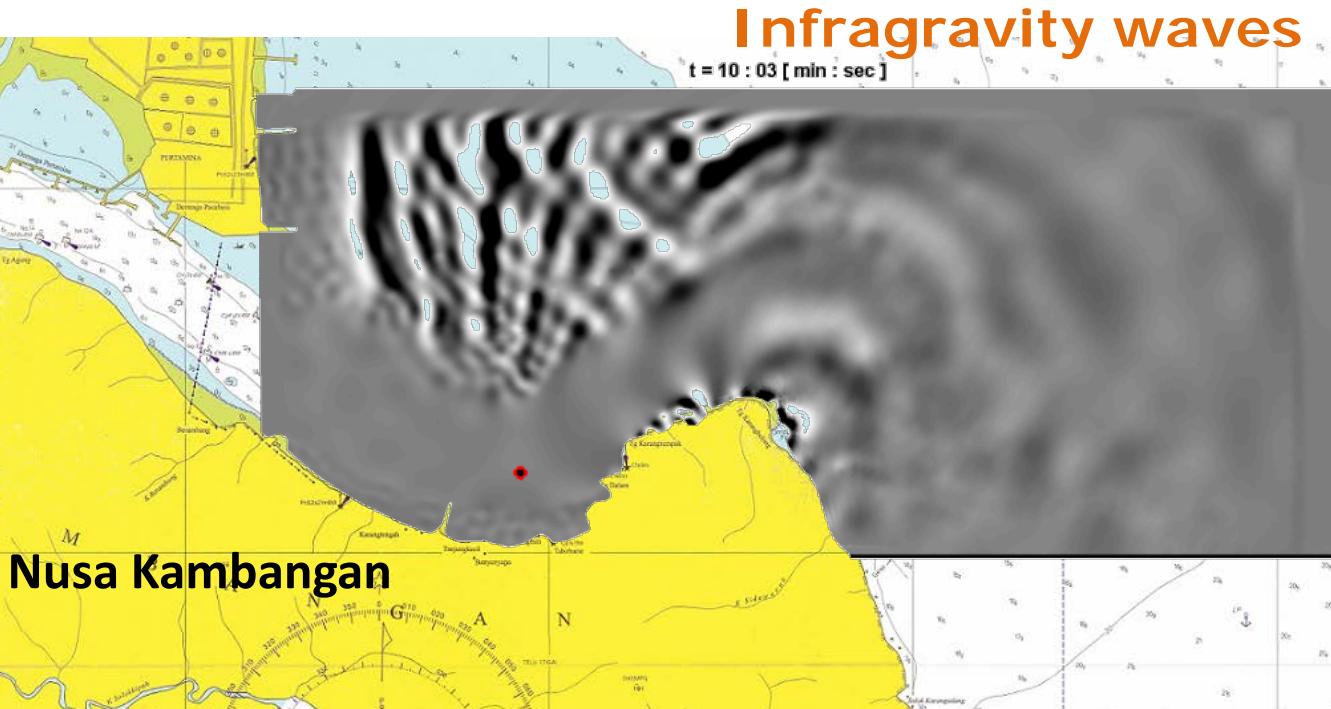
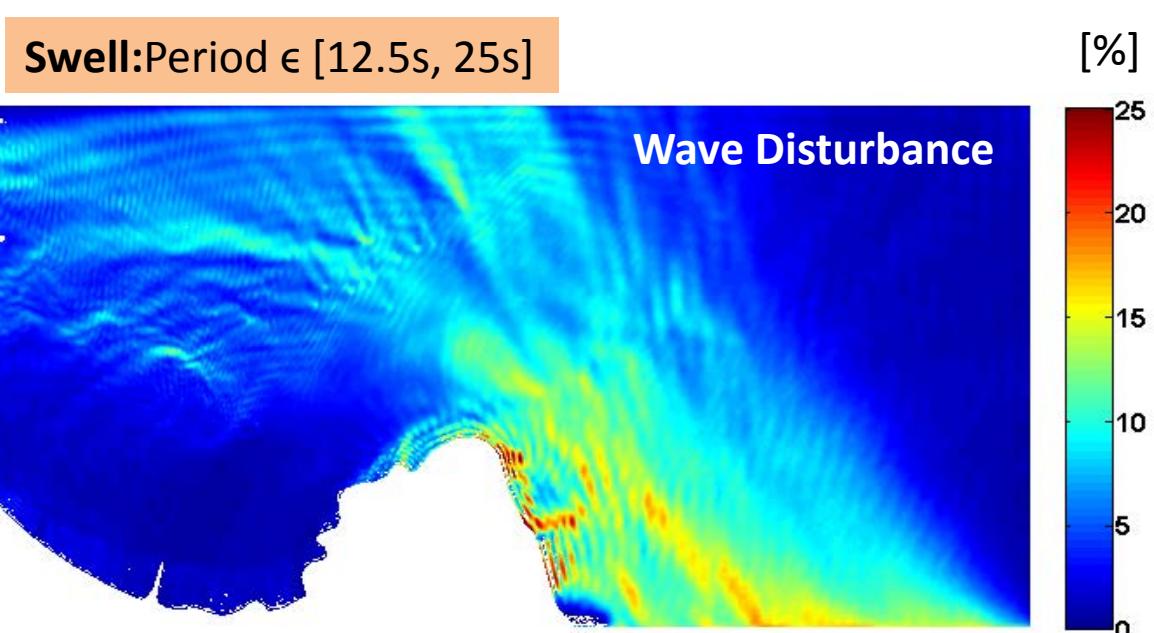
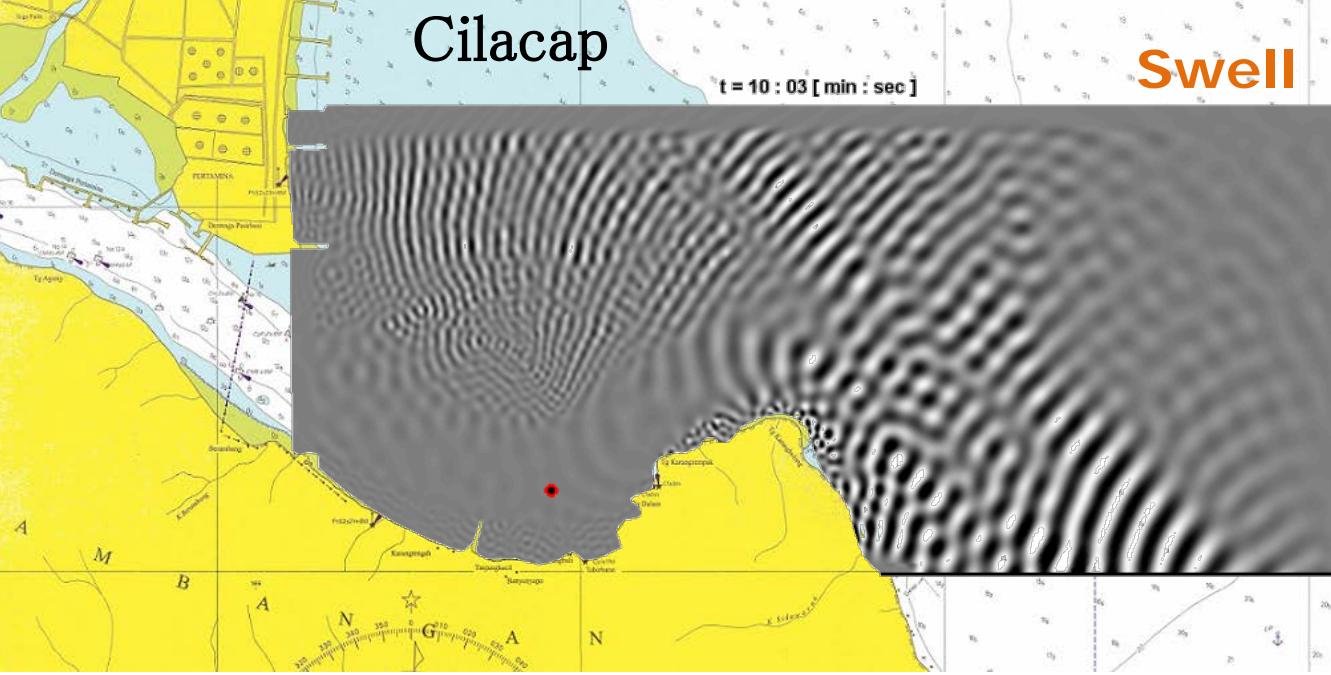


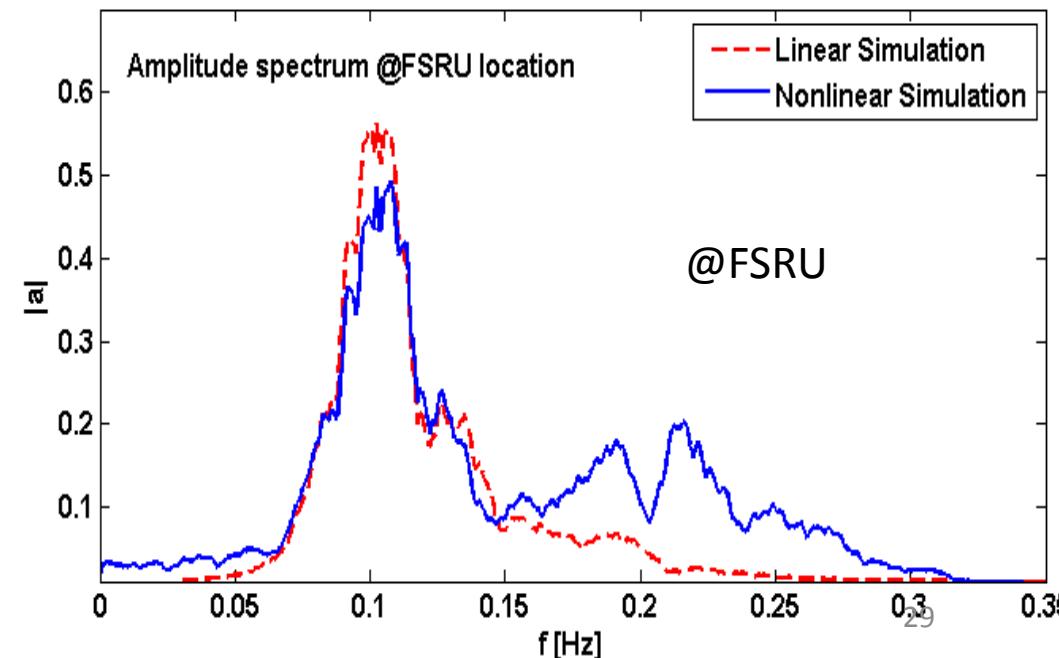
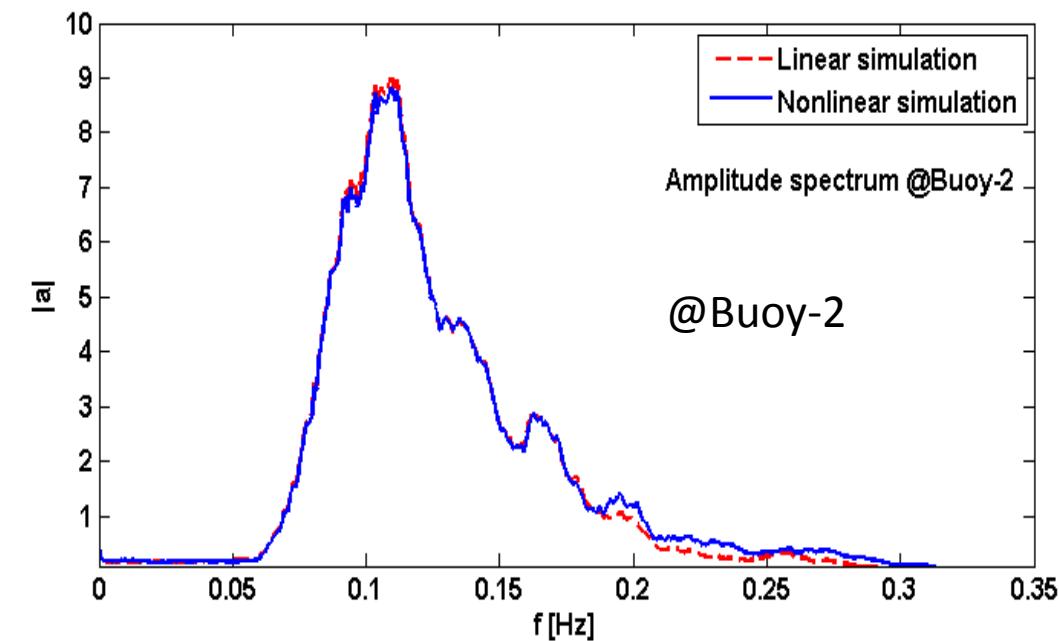
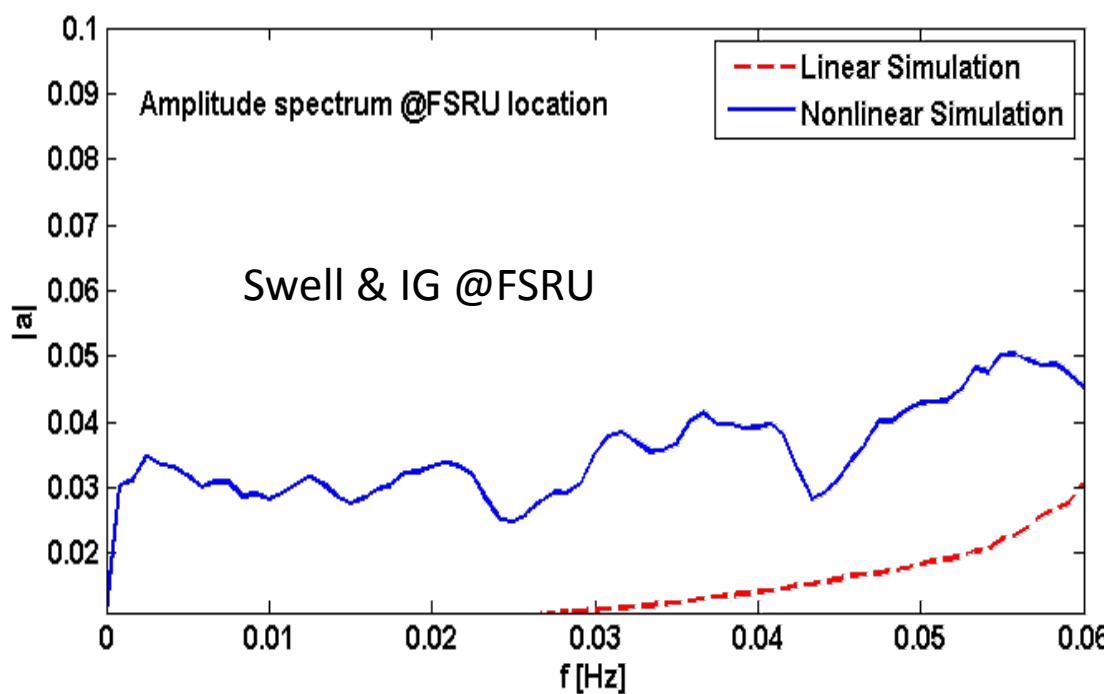
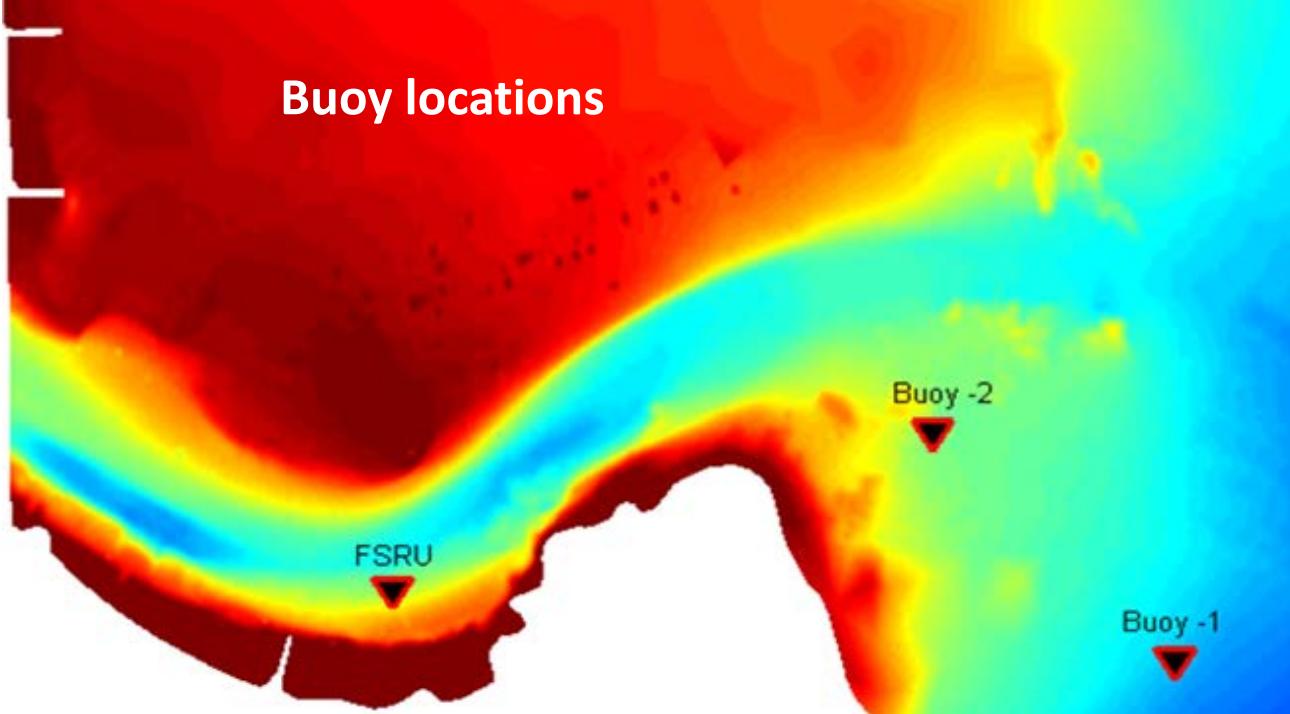


VBM simulations

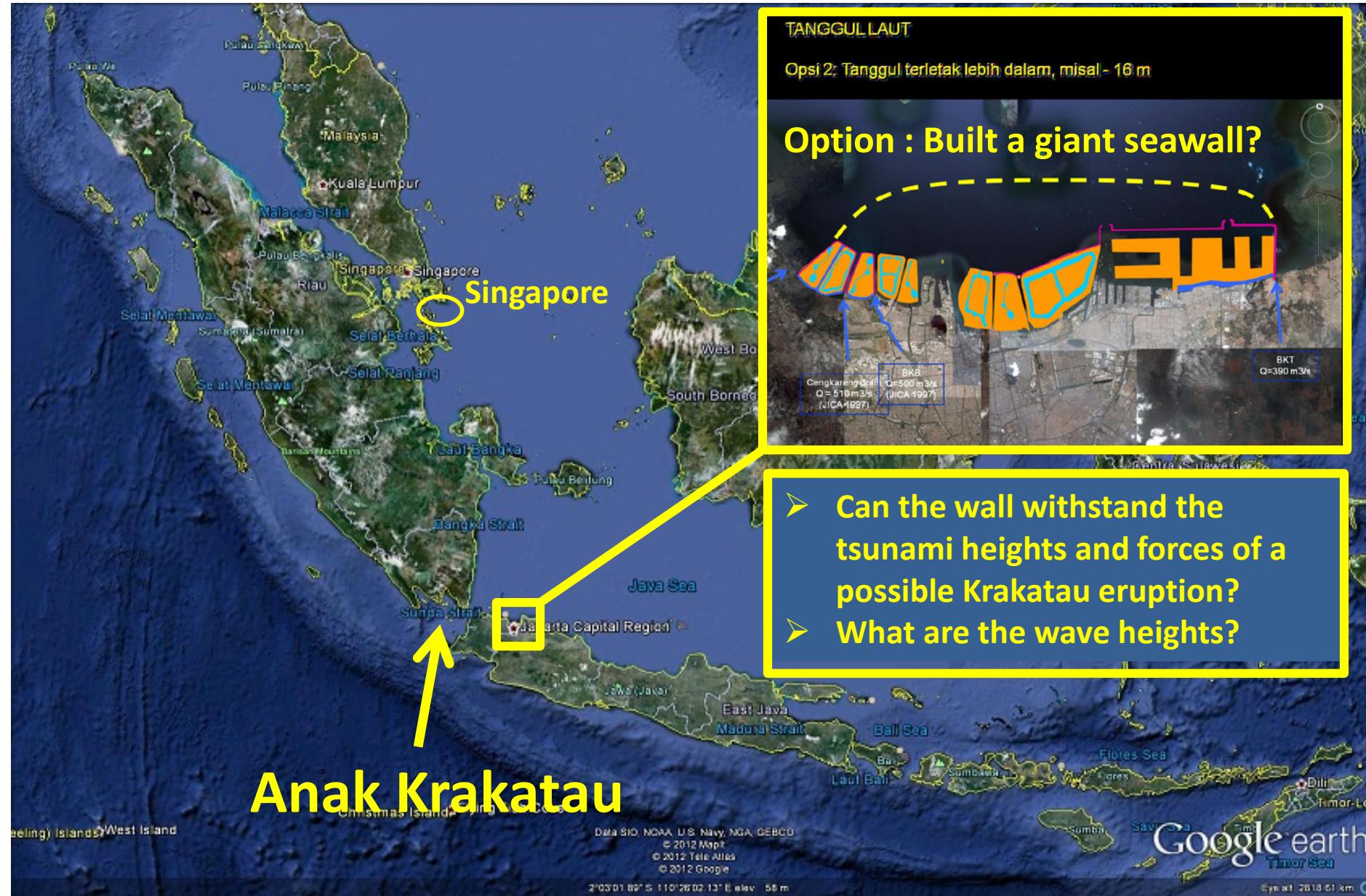
Bathymetry & Numerical settings







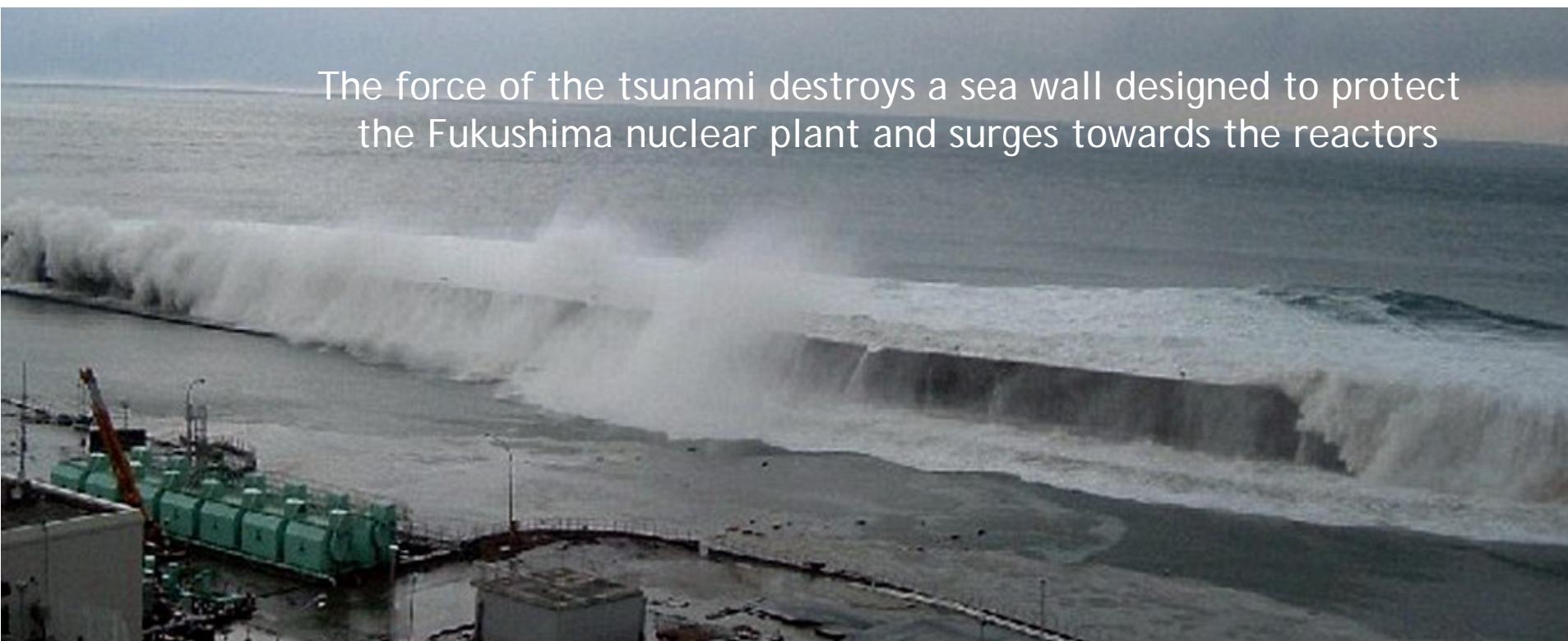
Jakarta, water problem





Witteveen+Bos

The force of the tsunami destroys a sea wall designed to protect the Fukushima nuclear plant and surges towards the reactors



Initial Condition: Inverse Problem

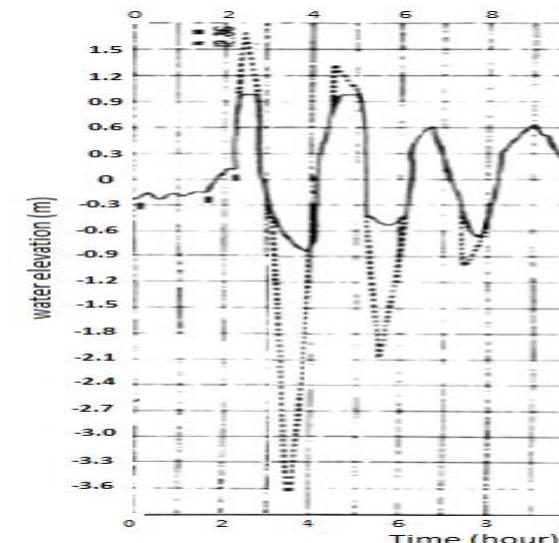
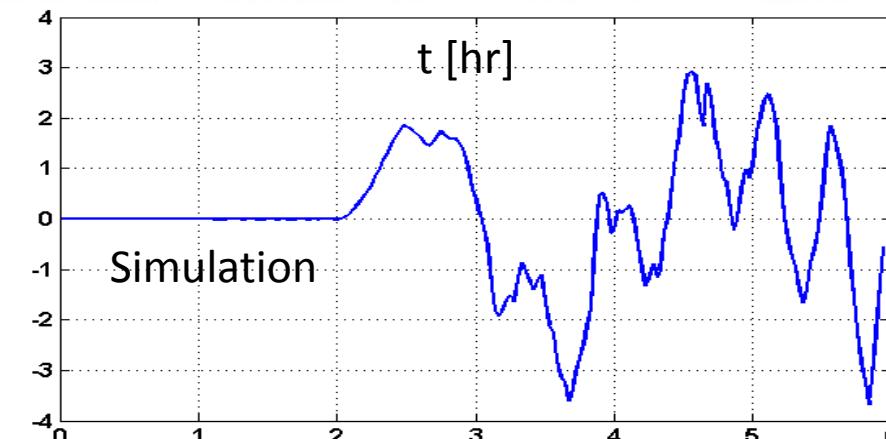
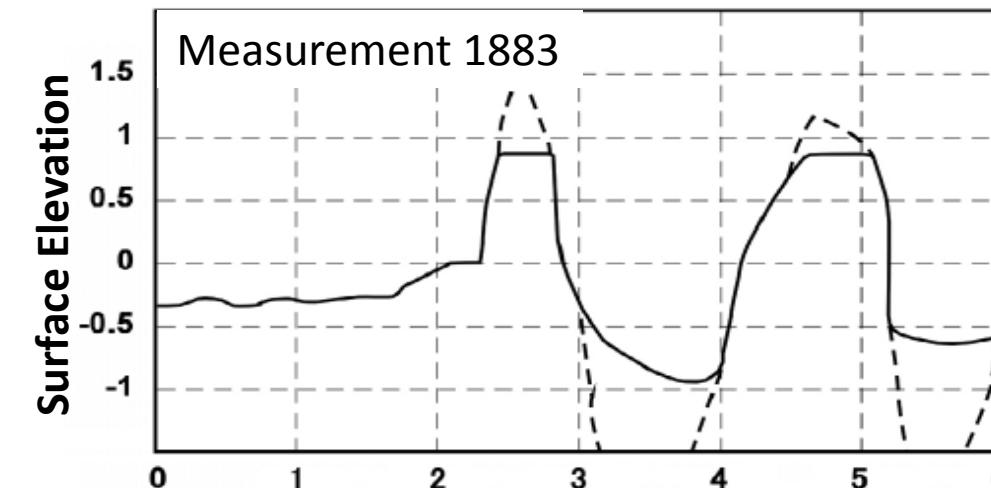
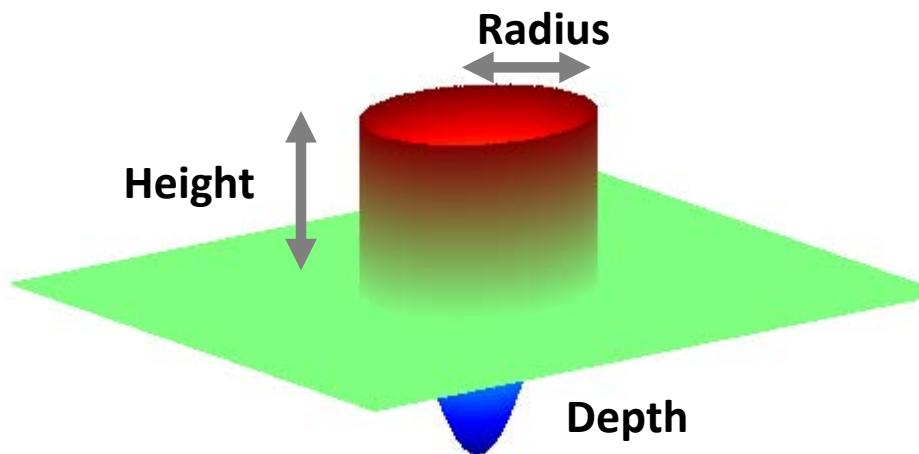
Find generation scenario

Simulation matches measurements near Batavia

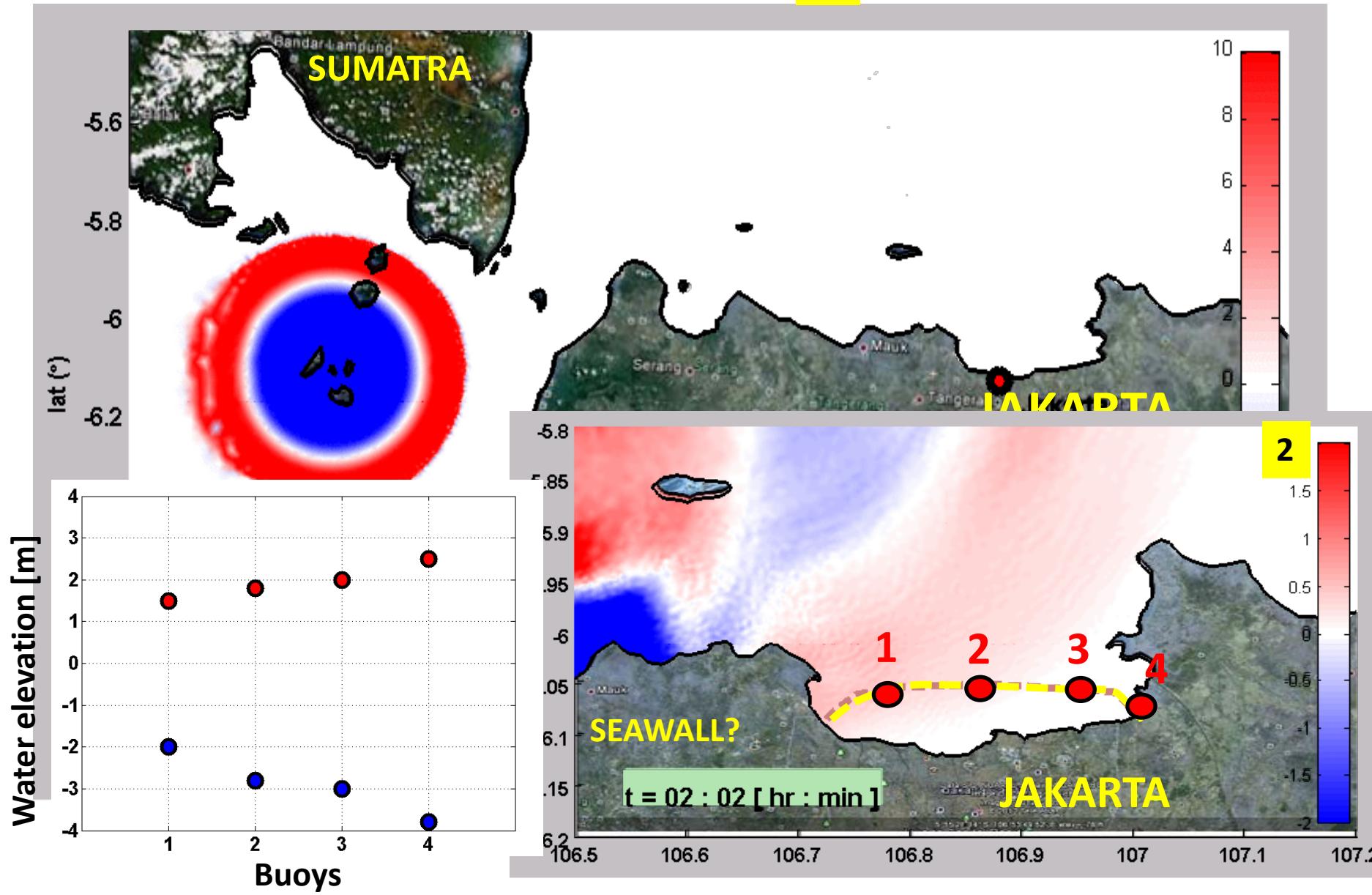
Maeno & Immamura [2011] :

- Use 3 models (for Initial Cond.)
- Pyroclastic flow gives best result

Phreato-magmatic



Reconstruction 1883 Krakatau Tsunami



Water Wave Theory

Basic Equations
Fluid Dynamics

17th Newton
18th Euler

Conservations : Mass and momentum
Compressible, incompressible flows

18th Laplace,
Cauchy, Airy

Initial value problem,
Linear wave theory

**Theory and
Models**

19th Stokes, Boussinesq
Korteweg –de Vries (KdV)
Scott Russel

Nonlinear Waves, Spatial reduction (Surface
water wave model), uni-directional waves.

Variational theory
Hamiltonian formulation

20th Bateman, Luke, Zakharov
Broer, Miles

Equations on surface,
model interior.
Consistent modelling

Hamiltonian Dynamics of surface waves, BASICS

Interior

Water is inviscid \rightarrow No dissipation, 'Conservative'

- Water is incompressible (constant density)
- ASSUME flow is irrotational

$$\left. \begin{array}{l} \operatorname{div} U = 0 \\ \operatorname{curl} U = 0 \Rightarrow U = \nabla \Phi(x, y, z) \end{array} \right\} \Delta \Phi(x, y, z) = 0$$

Free surface

Assume pressure free atmosphere

- Kinematic cn'd: continuity equation
- Bernoulli equation

$$\begin{aligned} \partial_t \eta(x, y, t) &= U \cdot N = \partial_N \Phi(x, y, \eta(x, t)) \\ \partial_t \Phi(x, y, \eta(x, t), t) &= \end{aligned}$$

Observation: can be described as system in

Class Mechanics, ***in surface variables only***

- Canonical variables
- Hamiltonian = Total Energy

$$\left. \begin{array}{l} \eta(x, y, t) \\ \phi(x, y, t) = \Phi(x, y, \eta(x, t), t) \\ H(\phi, \eta) = K(\phi, \eta) + \frac{1}{2} g \iint \eta^2(x, y) dx dy \end{array} \right\} \begin{array}{l} \partial_t \eta = \delta_\phi H(\phi, \eta) \\ \partial_t \phi = -\delta_\eta H(\phi, \eta) \end{array}$$

Difficulty

Approach (do NOT solve Laplace problem)

Consistent modelling through Dirichlet principle

KINETIC ENERGY

$$KE = \iint \int_{-D}^{\eta} \frac{1}{2} |U|^2 dz dx dy = ?? = K(\phi, \eta)$$

$$K(\phi, \eta) = \text{Min} \left\{ \iint \int_{-D}^{\eta} \frac{1}{2} |\nabla \Phi|^2 dz dx dy \middle| \Phi = \phi \text{ at } z = \eta \right\}$$

Consistent approximation Kinetic Energy

Analysis

Dirichlet's principle (1840)

$$K(\phi, \eta) = \text{Min} \left\{ \iint \int_{-D}^{\eta} \frac{1}{2} |\nabla \Phi|^2 dz dx dy \middle| \Phi = \phi \text{ at } z = \eta \right\}$$

Dirichlet-to-Neumann operator

$$\delta_\phi K(\phi, \eta) = \partial_N \Phi \text{ at } z = \eta$$

Consistent approximations

$$K(\phi, \eta) = \frac{1}{2g} \int (C \partial_x \phi)^2 dx$$

C is phase velocity operator

$$\delta_\phi K(\phi) = -\frac{1}{g} \partial_x C^2 \partial_x \phi$$

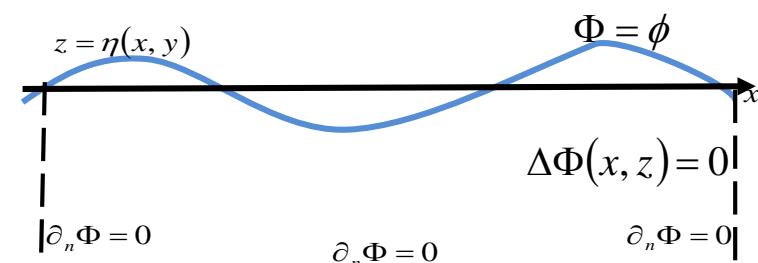
Approximate:

VBM: low-dim vertical structure, Finite Elements

AB: analytic with FIO (Fourier-Integral Operators), spatial-spectral

VBM Approximation Kinetic Energy (Avoid calculation of potentials in interior)

$$D(\Phi) = \iint_{-D}^{\eta} \int \frac{1}{2} |\nabla \Phi|^2 dz dx dy \quad K(\phi, \eta) = \text{Min}\{D(\Phi) | \Phi = \phi \text{ at } z = \eta\}$$



Consistent **VBM**-approximation: restrict minimizing set of functions

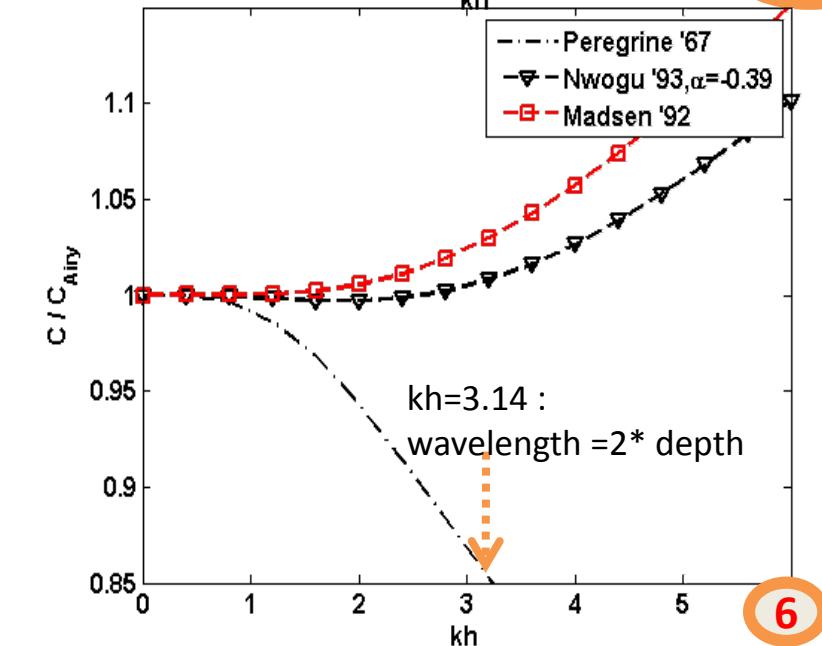
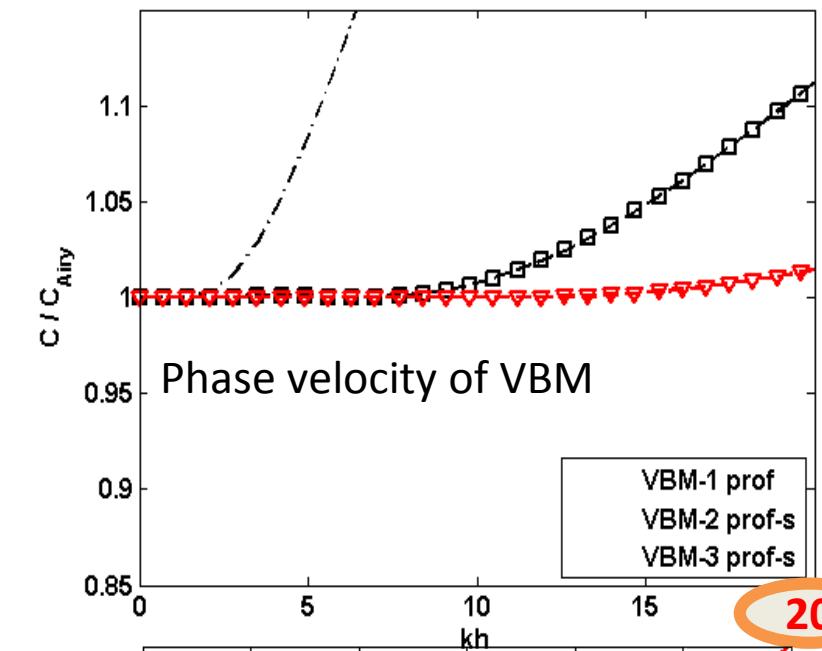
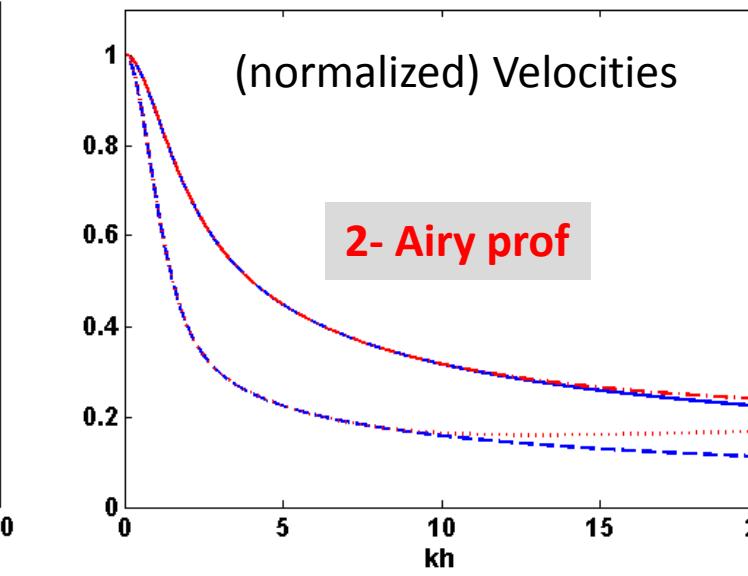
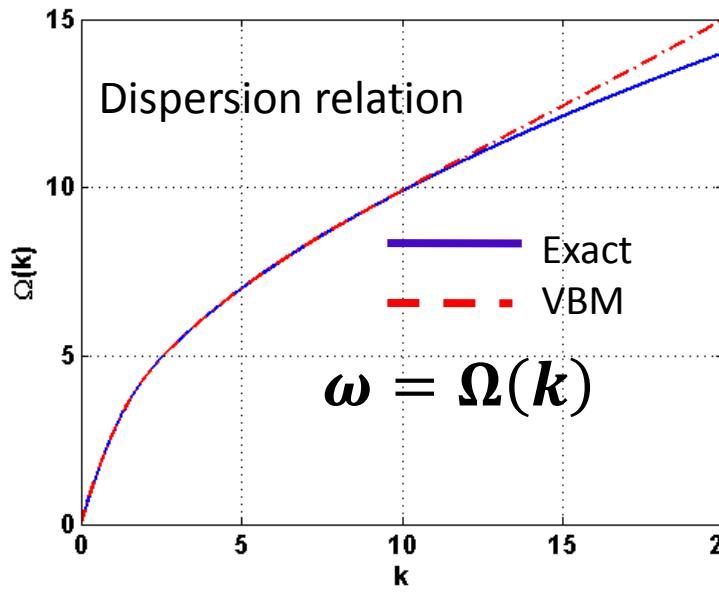
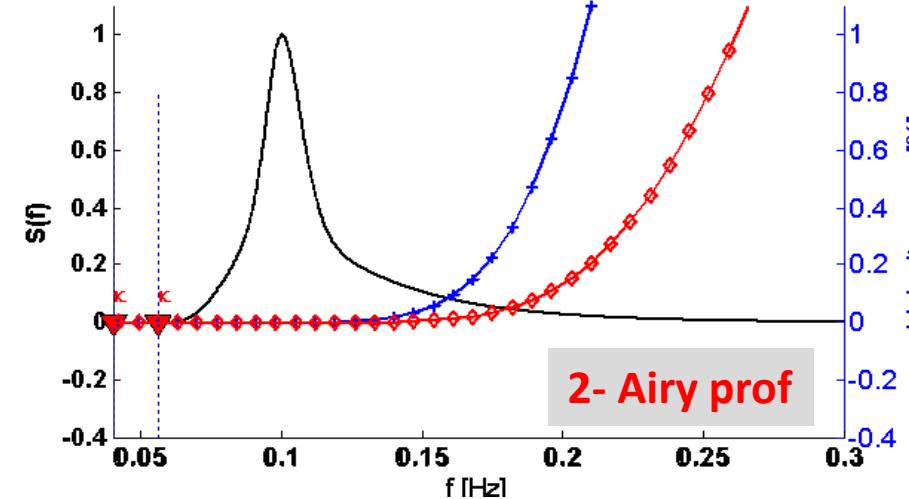
- Use as Ansatz $\Phi(x, z) = \phi(x) + F(z)\psi(x)$, with $F(\eta) = 0$; then $\Phi(x, \eta) = \phi(x)$
- Take $F(z)$ an Airy function $F(z) = 1 - \frac{\cosh(\kappa(z+D))}{\cosh(\kappa D)}$ with parameter κ
- Inserted in K leads to $K = K(\phi, \psi, \eta, \kappa)$
- Then $\delta_\psi K(\phi, \psi, \eta, \kappa) = 0$, elliptic eqn $\Rightarrow \psi = \psi(\phi)$
 $K_{VBM} = K(\phi, \psi(\phi), \eta, \kappa)$
- Optimize parameter κ depending on initial spectrum ! $\kappa \rightarrow K(..., \kappa) = \frac{g}{2} \int V_{VBM}(k(\omega), \kappa) S_0(\omega) d\omega$
- Combination of Airy functions possible to improve dispersion

Dispersive properties of Optimized VBM

$$K_{vbm} = \min_{\kappa} \min_{\psi} \left\{ \frac{1}{2} \iint_{-h}^{\eta} |\nabla \Phi|^2 dz d\underline{x} \mid \Phi = \phi + A(\kappa, z) \cdot \psi(\underline{x}) \right\}$$

$$A_m = \frac{\cosh(\kappa_m(z+h))}{\cosh(\kappa_m h)} - 1$$

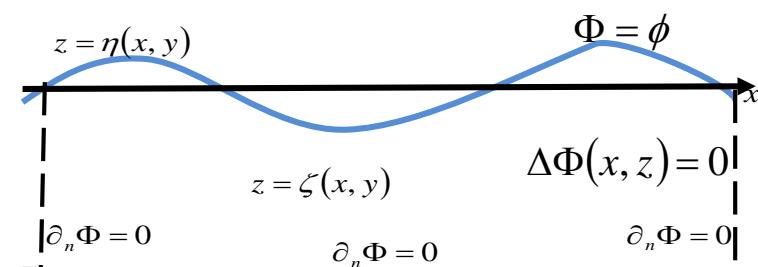
Tailor-made dispersion-relation
depending on wave spectrum



AB- Approximation Kinetic Energy (Avoid calculation of potentials in interior)

$$D(\Phi) = \iint_{-D}^{\eta} \int \frac{1}{2} |\nabla \Phi|^2 dz dx dy \quad K(\phi, \eta) = \text{Min}\{D(\Phi) | \Phi = \phi \text{ at } z = \eta\}$$

Consistent AB-approximation (spatial-spectral)



$$K(\phi, \eta) = \frac{1}{2g} \int (C \partial_x \phi)^2 dx$$

C is phase velocity operator

$$\delta_\phi K(\phi) = -\frac{1}{g} \partial_x C^2 \partial_x \phi$$

- Linear Airy theory: exact (dispersion) in strip

$$C^2 \doteq g \tanh(kD) \Big/ k \quad \delta_\phi K(\phi) \doteq k \tanh(kD) \hat{\phi}(k) \quad \text{Pseudo-Diff-Operator}$$

- Shallow water $C^2 = g(D(x) + \eta(x, t))$ $\delta_\phi K(\phi) = -\partial_x (D + \eta) \partial_x \phi$

- 2nd order above $D(x)$ $C^2 \doteq \left[g \tanh(kH) \Big/ k \right]_{\text{symm}}$ with $H = D(x) + \eta(x, t)$ Fourier-Int-Operator

Wave Breaking

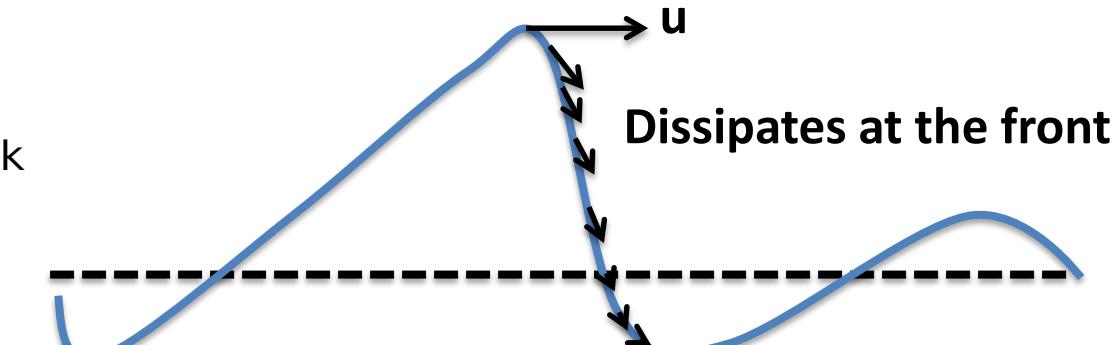
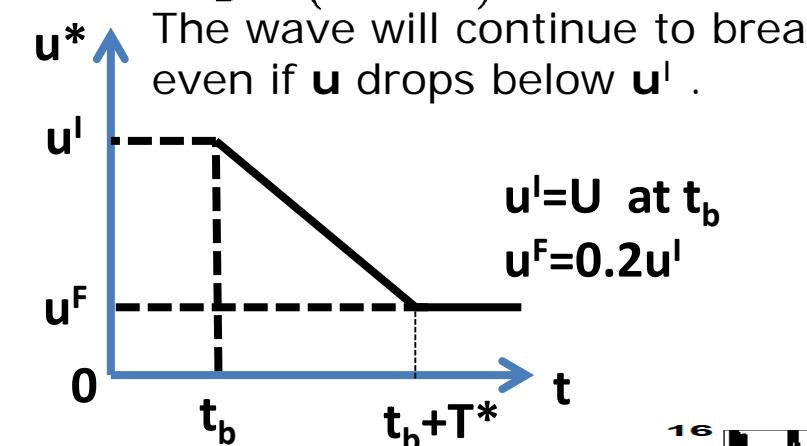
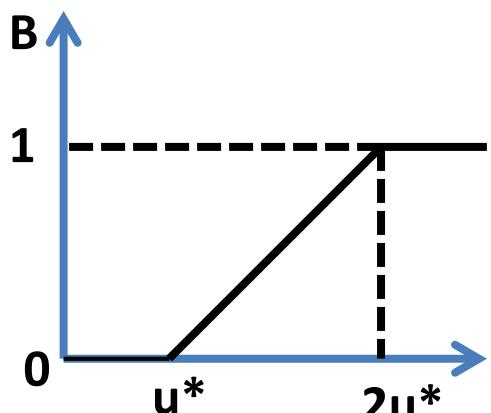
Eddy viscosity model

$$\partial_t u = \dots + R \quad R = \frac{1}{H} \partial_x F; \quad F = -v N; \quad v = B(u) \delta_B^2 H \cdot N; \quad N = \partial_t \eta, \quad H = D + \eta;$$

fully dispersive!

u : eddy viscosity localized at front of breaking wave

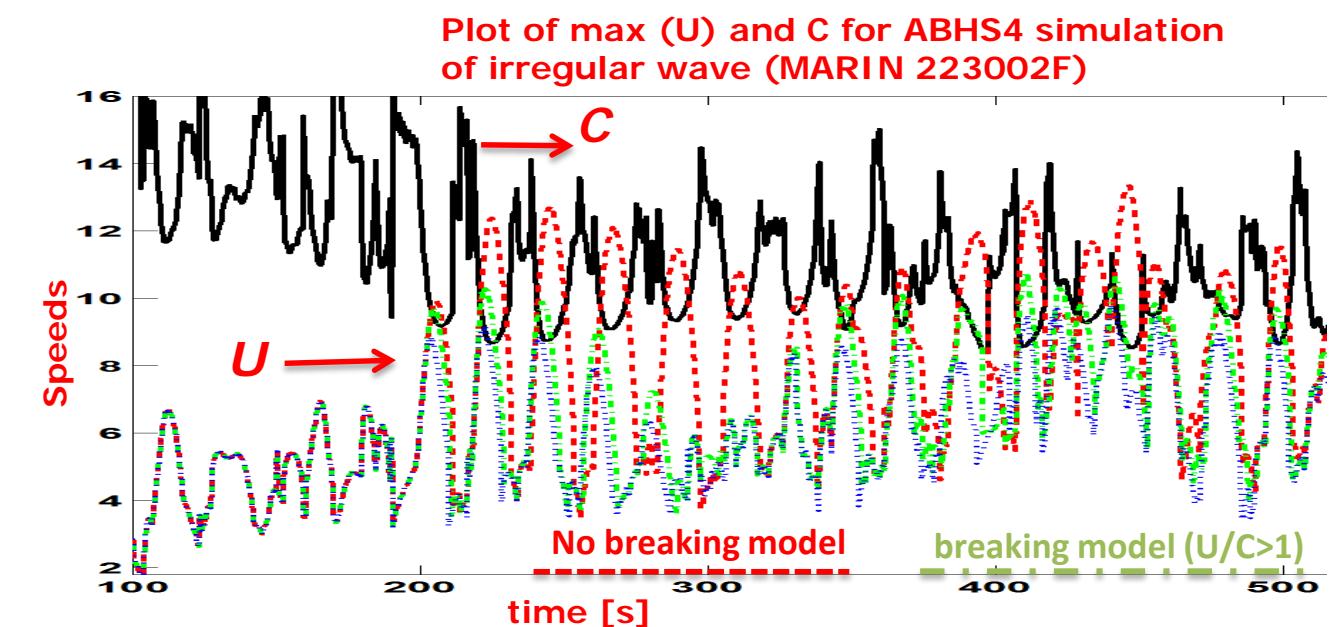
δ_B : mixing length coefficient; $\delta_B \in (0.9, 1.5)$



Kinematic breaking criterion:

particle velocity at crest (U) > Crest speed

Crest speed $C(x_c, t) = \sqrt{g \tanh(k(x_c, t)D) / k(x_c, t)}$
 with $k(x, t) = \frac{\partial}{\partial x} \theta(x, t)$



Conclusions

- AB and VBM in horizontal variables only (Boussinesq reduction)
 - Practical use of Dirichlet principle by consistent approximation:
→ *all symmetry properties are retained, robust*
 - AB: FIO's are 'expensive' but efficient approximation by *interpolation* techniques
 - VBM: optimized dispersion, more profiles more expensive
- Performance is satisfying/good compared to experiments; at present:
 - AB most suitable for wave tank simulations ('fast')
 - VBM for coastal applications
- Extension to wave-ship interaction in progress

**Announcement: HaWaSI VBM and AB
will become available in 2015**
(advanced options for tailor-made license)

We like to hear your coastal eng
problems and are interested to
collaborate

The advancement of Mathematics has profited tremendously from study of Fluid Mechanics / waves

➤ **Asymptotics:**

- bdy-layers → (matched) asymptotic expansions
- WKB asymptotics
- characteristics (Hamilton-Jacobi)

MathProfits

➤ **Infinite dimensionality** → Hilbert (Courant & Hilbert)

- functionals (var principles Maupertuis, Euler/Dirichlet)
- gen solutions pde: shock relations

➤ **Dyn. System theory & pde**

- complete integrability ('65 KdV)
- Nonlinearity: Fermi Pasti-Ulam
- Topological study of nonlin problems (Poincare, Lax)

➤ **Numerics:**

- fem (static → dynamic),
- vof (balance laws),
- Kruskal & Zabusky '67

➤ **Modelling:**

- balance (conservation) laws
- optimization formulations
- Ham-consistent modelling & numerics

Acknowledgements



Recent Publications

- R. Kurnia & EvG, MARHY 2014, Chennai
Lie S Liam, D. Adytia & EvG, *Ocean Eng.* 2014
R. Kurnia & EvG, *Coastal Eng.* 2014
D. Adytia & EvG, *J. Coastal Eng.* 2012
EvG & Andonowati, *Wave Motion* 2011
A.L. Latifah & EvG, *Nonlin. Processes Geophys* 2012
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Acknowledgements



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